

Programmable Controller CJ-series

Serial (RS-232C) Communications Connection Guide

OMRON Corporation Auto Focus Multi Code Reader V320-F / V420-F / V430-F-series

Network Connection Guide

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1. Related Manuals

The following manuals are related to this document.

To ensure system safety, make sure to always read and follow the information provided in all Safety Precautions and Precautions for Safe Use in the manuals for each device which is used in the system.

| Cat. No. | Model | Manual name | |
|----------|------------------------------------|---|--|
| W472 | CJ2H-CPU6□-EIP | CJ-series | |
| | CJ2H-CPU6□ | CJ2 CPU Unit | |
| | CJ2M-CPU□□ | Hardware User's Manual | |
| W473 | CJ2H-CPU6□-EIP | CJ-series | |
| | CJ2H-CPU6□ | CJ2 CPU Unit | |
| | CJ2M-CPU□□ | Software User's Manual | |
| W336 | CJ1W-SCU□1-V1 | CJ-series | |
| | CJ1W-SCU□2 | Serial Communications Boards/Units | |
| | | Operation Manual | |
| W446 | CXONE-AL _□ C-V4 / | CX-Programmer Operation Manual | |
| | AL□□D-V4 | | |
| W344 | CXONE-AL _□ C-V4 / | CX-Protocol Operation Manual | |
| | AL _□ D-V4 | | |
| W474 | CJ2 _□ -CPU _□ | CJ-series | |
| | | Instructions Reference Manual | |
| Z432 | V320-F/V330-F/V420-F/ | MicroHAWK V320-F/V330-F/V420-F/V430-F | |
| | V430-F Series | Series Barcode Reader User Manual | |
| Z407 | V320-F/V330-F/V420-F/ | Autofocus Multicode Reader MicroHAWK | |
| | V430-F Series | V320-F/V330-F/V420-F/V430-F Series User | |
| | | Manual for Communication Settings | |

2. Terms and Definitions

| Term | Description/Definition |
|------------------|--|
| Protocol Macro | This function enables data send/receive with general-purpose external |
| | devices by storing the data send/receive procedure (Protocol) used with |
| | the general-purpose external devices in the Serial Communication Board |
| | or Unit and executing the PMCR instruction in the CPU Unit. |
| Protocol | The unit that comprises an independent communication processing for a |
| | specific general-purpose external device as a data send/receive procedure |
| | is called a "Protocol". A "protocol" consists of two or more sequences. |
| Sequence | A unit of independent communication processing that can be activated |
| | from the PMCR instruction on the ladder program. When activated, the |
| | steps in the sequence are executed sequentially. |
| Step | A unit to execute processing, which is send message, receive message, |
| | send and receive message, clear receive buffer, or step queuing. Up to 15 |
| | steps can be set in a sequence. |
| Send Message | A communication frame (command) sent to a general-purpose external |
| | device. It is called from a step in a sequence and sent to a general-purpose |
| | external device. |
| Receive Message | A communication frame (response) sent from a general-purpose external |
| | device. It is called from a step in a sequence and compared with data |
| | received from the general-purpose external device. |
| Reception Matrix | A reception matrix is used when it is impossible to uniquely identify |
| | communication frames (responses) sent from a general-purpose external |
| | device. In a reception matrix, more than one communication frame can be |
| | registered. |
| Case | A unit for registering multiple communication frames (responses) in a |
| | reception matrix. One communication frame is registered as one case. Up |
| | to 15 cases can be registered in a reception matrix. |

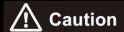
3. Restrictions and Precautions

- (1) Before building a system, understand the specifications of devices which are used in the system. Allow some margin for ratings and performance, and provide safety measures such as installing a safety circuit in order to minimize the risk in case of failure.
- (2) To ensure system safety, make sure to read and follow the information provided in all Safety Precautions and Precautions for Safe Use in the manuals for each device which is used in the system.
- (3) The user is encouraged to confirm the standards and regulations that the system must conform to.
- (4) It is prohibited to copy, to reproduce, and to distribute a part or the whole of this document without the permission of OMRON Corporation.
- (5) The information contained in this document is current as of February 2023. It is subject to change for improvement without notice.

The following notations are used in this document.



Indicates a potentially hazardous situation which, if not avoided, may result in minor or moderate injury, or may result in serious injury or death. Additionally, there may be severe property damage.



Indicates a potentially hazardous situation which, if not avoided, may result in minor or moderate injury, or property damage.



Precautions for Safe Use

Precautions on what to do and what not to do to ensure safe usage of the product.



Precautions for Correct Use

Precautions on what to do and what not to do to ensure proper operation and performance.



Note

Additional information to read as required.

This information is provided to increase understanding or make operation easier.

Symbols



The filled circle symbol indicates operations that you must do.

The specific operation is shown in the circle and explained in text.

This example shows a general precaution for something that you must do.

4. Overview

This document describes the procedures for connecting the OMRON code reader products (V320-F/V420-F/V430-F Series) to a CJ Series Programmable Controller with a Serial Communications Unit (hereinafter referred to as PLC) via serial communications and for checking their connections.

Refer to Section 6. Serial Communication Settings and Section 7. Connection Procedure to understand the setting procedures and key points of setup to establish a serial communications connection.

Using the user program in the "CX-Programmer Project File" and the protocol data in the "CX-Protocol Project File" prepared in advance, use the "Read trigger" command for the code reader to check the serial communications connection.

Obtain the latest versions of the CX-Programmer Project File and CX-Protocol Project File in advance. Contact OMRON for information on how to obtain these files.

| Name | Filename | Version |
|--------------------------|----------------------------------|-----------|
| CX-Programmer Project | OMRON_V320_V420_V430_PMCR232C_V | Ver. 1.00 |
| File (Extension: cxp) | 100.cxp | |
| CX-Protocol Project File | OMRON_V320_V420_V430_PMCR_V100.p | Ver. 1.00 |
| (Extension: psw) | sw | |

^{*} Hereinafter, the CX-Programmer Project File is called "project file".

The user program in a project file is called "ladder program" or "program".

The CX-Protocol Project File is called "protocol macro data".

∕ Caution

The purpose of this document is to describe the wiring methods, communication settings, and setting procedures required to establish a connection for communications with applicable devices. In addition, the program used in this document is designed to check that the connection has been correctly performed (connection check). Since the program is not intended for permanent use on-site, full consideration is not given to functionality and performance. When configuring an actual system, please refer to the wiring methods, communication settings, and setting procedures described in this document to design and create a program that meets your purpose.



5. Applicable Devices and Support Tools

5.1. Applicable Devices

The applicable devices that can be connected are as follows:

| Manufact urer | Name | Model | Version |
|------------------|----------------------------|------------------------------------|---------------------|
| OMRON | CJ2 CPU Unit | CJ2 _□ -CPU _□ | Same or |
| OMRON | Serial Communications Unit | CJ1W-SCU□1-V1 CJ1W-SCU□2 | later version as |
| OMRON | Code reader | V320-Fananana-ana | indicated in |
| | | V420-Fananana-ana | section |
| | | V430-Faaaaaaa-aaa | 5.2. |



Note

From among the above applicable devices, this document uses the devices listed in section 5.2 for the connection check. When using devices that are not described in section 5.2, check the connection according to this document.



Note

This document describes the procedures for establishing the communication connection of the device, and does not describe the operation, installation and wiring method of the device. For details on the above products (other than communication connection procedures), please refer to the instruction manual for the product or contact OMRON.



Precautions for Correct Use

The connection and connection check procedures described in this document use the devices listed in section 5.2, from among the above applicable devices.

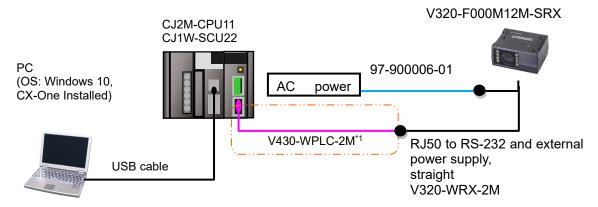
You cannot use devices with versions earlier than the versions listed in section 5.2.

To use models that are not listed in section 5.2. or versions that are later than those listed in section 5.2., check the differences in the specifications according to their instruction manuals before operating the devices.

5.2. Device Configuration

The system components required for reproducing the connection procedures described in this document are as follows.

Configuration with V320-F



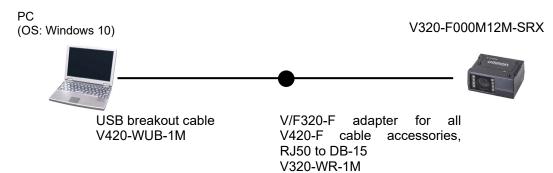
| Manufact | Name | Model | Version |
|----------|--|--|------------|
| urer | | | |
| OMRON | CPU Unit | CJ2M-CPU11 | Ver. 2.0 |
| OMRON | Serial Communications Unit | CJ1W-SCU22 | Ver. 2.0 |
| OMRON | Power Supply Unit | CJ1W-PA202 | |
| OMRON | CX-One | CXONE-AL==C-V4 /AL==D-V4 | Ver. 4.□□ |
| OMRON | CX-Programmer | (Included with CX-One) | Ver. 9.66 |
| OMRON | CX-Protocol | (Included with CX-One) | Ver. 1.993 |
| OMRON | CX-Programmer Project File (Ladder Program) | OMRON_V320_V420_V 430_PMCR232C_V100. cxp | Ver. 1.00 |
| OMRON | CX-Protocol Project File (Protocol macro data) | OMRON_V320_V420_V 430_PMCR_V100.psw | Ver. 1.00 |
| | PC (OS: Windows 10) | | |
| | USB cable (USB 2.0-compliant B-type connector) | | |
| OMRON | Code reader | V320-F000M12M-SRX | Ver. 2.1.0 |
| OMRON | RJ50 to RS-232 and external power supply, straight | V320-WRX-2M | |
| OMRON | OMRON Programmable Controller (CS/CJ/NJ) RS-232C cable | V430-WPLC-2M*1 | |
| OMRON | Power supply | 97-900006-01 | |
| *4.5.6.1 | AC power supply | # DO 0000 11 | 15 |

^{*1.} Refer to 6.2. Cable Wiring Diagram for how to prepare the RS-232C cable yourself.

5. Applicable Devices and Support Tools

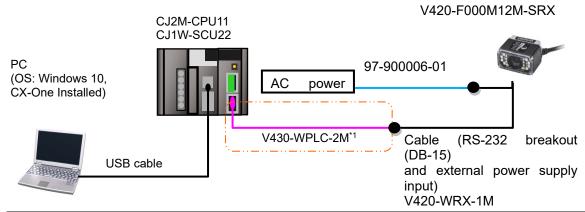
WebLink cannot be used for RS-232C connection.

To use WebLink, the following system components for USB connection are required.



| Manufact | Name | Model | Version |
|----------|--|-------------------|------------|
| urer | | | |
| | PC (OS: Windows 10) | | |
| OMRON | Code reader | V320-F000M12M-SRX | Ver. 2.1.0 |
| OMRON | V/F320-F adapter for all V420-F cable accessories, RJ50 to DB-15 | V320-WR-1M | |
| OMRON | USB breakout cable | V420-WUB-1M | |

Configuration with V420-F



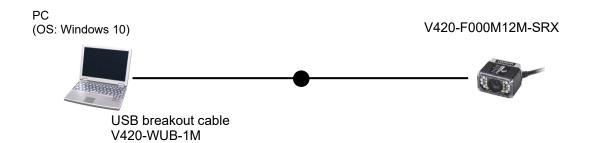
| Manufact | Name | Model | Version |
|----------|---|---|------------|
| urer | | | |
| OMRON | CPU Unit | CJ2M-CPU11 | Ver. 2.0 |
| OMRON | Serial Communications Unit | CJ1W-SCU22 | Ver. 2.0 |
| OMRON | Power Supply Unit | CJ1W-PA202 | |
| OMRON | CX-One | CXONE-AL _□ C-V4 /AL _□ D-V4 | Ver. 4.□□ |
| OMRON | CX-Programmer | (Included with CX-One) | Ver. 9.66 |
| OMRON | CX-Protocol | (Included with CX-One) | Ver. 1.993 |
| OMRON | CX-Programmer Project File (Ladder Program) | OMRON_V320_V420_V 430_PMCR232C_V100. cxp | Ver. 1.00 |
| OMRON | CX-Protocol Project File (Protocol macro data) | OMRON_V320_V420_V 430 PMCR V100.psw | Ver. 1.00 |
| | PC (OS: Windows 10) | | |
| | USB cable (USB 2.0-compliant B-type connector) | | |
| OMRON | Code reader | V420-F000M12M-SRX | Ver. 2.1.0 |
| OMRON | Cable (RS-232 breakout (DB-15) and external power supply input) | V420-WRX-1M | |
| OMRON | OMRON Programmable Controller (CS/CJ/NJ) RS-232C cable | V430-WPLC-2M*1 | |
| OMRON | Power supply | 97-900006-01 | |
| | AC power supply | | |

^{*1.} Refer to 6.2. Cable Wiring Diagram for how to prepare the RS-232C cable yourself.

5. Applicable Devices and Support Tools

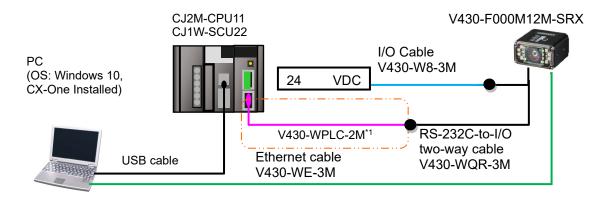
WebLink cannot be used for RS-232C connection.

To use WebLink, the following system components for USB connection are required.



| Manufact | Name | Model | Version |
|----------|---------------------|-------------------|------------|
| urer | | | |
| | PC (OS: Windows 10) | | |
| OMRON | Code reader | V420-F000M12M-SRX | Ver. 2.1.0 |
| OMRON | USB breakout cable | V420-WUB-1M | |

Configuration with V430-F



| Manufact | Name | Model | Version |
|----------|--------------------------------------|---|------------|
| urer | | | |
| OMRON | CPU Unit | CJ2M-CPU11 | Ver. 2.0 |
| OMRON | Serial Communications Unit | CJ1W-SCU22 | Ver. 2.0 |
| OMRON | Power Supply Unit | CJ1W-PA202 | |
| OMRON | CX-One | CXONE-AL _□ C-V4 /AL _□ D-V4 | Ver. 4.□□ |
| OMRON | CX-Programmer | (Included with CX-One) | Ver. 9.66 |
| OMRON | CX-Protocol | (Included with CX-One) | Ver. 1.993 |
| OMRON | CX-Programmer Project File (Ladder | OMRON_V430_PMCR2 | Ver. 1.00 |
| | Program) | 32C_V100.cxp | |
| OMRON | CX-Protocol Project File | OMRON_V430_PMCR_ | Ver. 1.00 |
| | (Protocol macro data) | V100.psw | |
| | PC (OS: Windows 10) | | |
| | USB cable | | |
| | (USB 2.0-compliant B-type connector) | | |
| OMRON | Code reader | V430-F000M12M-SRX | Ver. 2.1.0 |
| OMRON | RS-232C-to-I/O two-way cable | V430-WQR-3M | |
| OMRON | OMRON Programmable Controller | V430-WPLC-2M*1 | |
| | (CS/CJ/NJ) RS-232C cable | | |
| OMRON | I/O Cable | V430-W8-3M | |
| OMRON | Ethernet cable | V430-WE-3M | |
| | 24 VDC power supply | | |

^{*1.} Refer to 6.2. Cable Wiring Diagram for how to prepare the RS-232C cable yourself.



Precautions for Correct Use

Obtain the latest versions of the project file and protocol macro data in advance. Contact OMRON for information on how to obtain these files.



Precautions for Correct Use

Ensure that the CX-Programmer and CX-Protocol are updated to the versions specified in this section or higher. If you use a version other than the version specified in this section, there may be differences in the procedures in Section 7 and later. In that case, refer to the *CX-Programmer Operation Manual* (Cat. No. W446) or *CX-Protocol Operation Manual* (Cat. No. W344) to perform the equivalent procedures.



Note

The configuration may not be reproduced if the system component models or versions differ. Check your configuration and, if there is any difference in the models or versions, contact OMRON.



Note

This document assumes that the USB is used to connect the PLC. For information on how to install the USB driver, refer to the *CX-Programmer Operation Manual* (Cat. No. W446).



Note

Refer to the *Industrial Switching Hub W4S1 Series User Manual* (0969584-7) for power supply specifications that can be used for 24 VDC power supply (for the switching hub).



Note

Refer to the MicroHAWK V320-F/V330-F/V420-F/V430-F Series Barcode Reader User Manual (Cat. No. Z432) for the power supply specifications that can be used for 24 VDC power supply (for the code reader).

6. Serial Communications Settings

This section shows the specifications of the communication parameter settings, cable wiring, and other information provided in this document.



Note

You need to modify the program to use communication settings that are not described in this section. For more information on the program, please refer to *Section 9. Program*.

6.1. Serial Communications Settings

The serial communications settings are as follows.

| Parameter name | SCU Unit* | Code reader |
|-----------------------------|---------------------|---------------------------|
| Unit number | 0 | |
| Communications | Port 2 (RS-232C) | |
| (connection) port | | |
| Serial communications mode | Protocol macro | |
| Data length | 8 bits | 8 bits (default) |
| Stop bit | 1 bit | 1 bit (default) |
| Parity | None | None (default) |
| Baud rate | 9,600 bps (default) | 9,600 bps |
| Protocol macro transmission | Full-duplex | |
| method | | |
| Header | | None (default) |
| Footer | | <cr+lf> (default)</cr+lf> |
| Host port protocol | | Point-to-point (default) |

^{*} SCU Unit: Serial Communications Unit



Precautions for Correct Use

It is assumed that the CJ1W-SCU22 Serial Communications Unit is used with the unit number is 0 and the communications (connection) port *Port* 2. If using other conditions to connect the Unit, refer to *Section 9. Program* and create a program by modifying the control data in the CIO Area and PMCR Instruction.

6.2. Cable Wiring Diagram

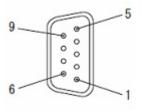
For details on cable wiring, refer to Section 3 Installation and Connection in the CJ-series Serial Communications Boards/Units Operation Manual (Cat. No. W336).

Check the connector shape and signal lines (pin assignment) before you prepare the cable.

■ Connector Shape and Signal Lines (Pin Assignment)

Applicable connector for CJ1W-SCU22: D-SUB 9-pin (Connector shape on CJ1W-SCU22 side: Female)

| Pin No. | Abbreviation | Signal name | I/O |
|---------|--------------|---------------------|--------|
| 1 | FG | Shield | |
| 2 | SD | Send data | Output |
| 3 | RD | Receive data | Input |
| 4 | RS | Request to send | Output |
| 5 | CS | Clear to send | Input |
| 6 | 5V | Power supply | |
| 7 | DR | Data set ready | Input |
| 8 | ER | Data terminal ready | Output |
| 9 | SG | Signal ground | |
| Shell | FG | Shield | |

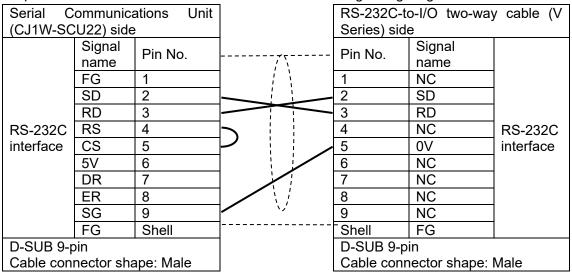


Applicable connector for V Series RS-232C cable: D-SUB 9-pin (Connector on V Series side: Female)

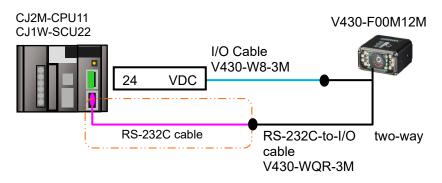
| Pin No. | Signal name | Pin assignment |
|---------|-------------|----------------|
| 1 | - | |
| 2 | SD | |
| 3 | RD | (0)/ |
| 4 | - | 601 |
| 5 | 0V | 3 |
| 6 | - | 11884 |
| 7 | - | |
| 8 | - | |
| 9 | - | |

■ RS-232C Cable Pin Assignment

Prepare the RS-232C cable with reference to the following wiring diagram.



For V430-F

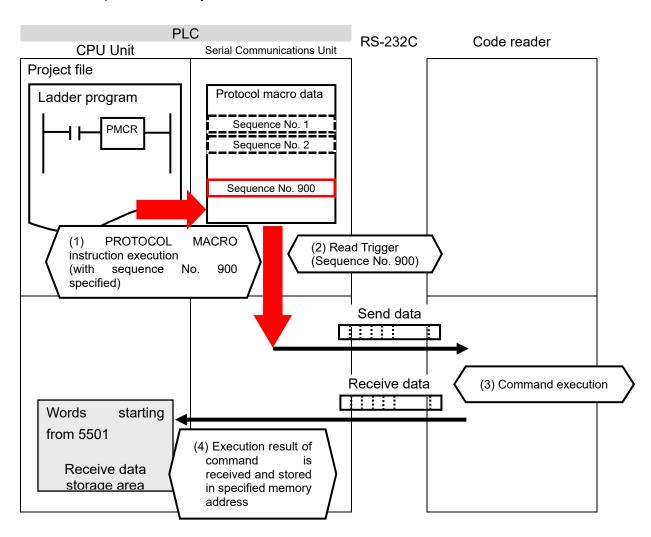


6.3. Example of Connection Check for Communications

In this document, an example of sending and receiving messages between the controller and the code reader using a ladder program and protocol macro data is given.

Between the PLC and the code reader, the "Execute Read (Sequence No. 900)" message is sent and received. An overview of the sequence operation is shown below.

- Sequence Operation Overview
 - (1) In the ladder program, the PROTOCOL MACRO instruction (PMCR instruction) is executed with sequence No. 900 of the protocol macro data specified.
 - (2) "Read trigger" command is selected from sequence No. 900 of the protocol macro data and sent to the code reader.
 - (3) The code reader executes the command according to the data sent from the PLC.
 - (4) The PLC receives the execution result of the command from the code reader and stores it in the specified memory address.



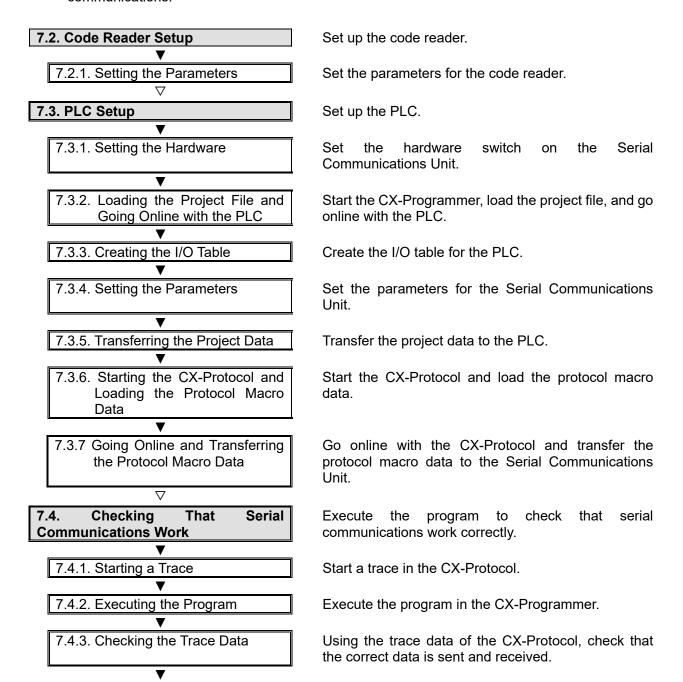
7. Connection Procedure

This section describes the procedures for connecting the code reader to the PLC for serial communications.

In this document, it is assumed that the PLC and the code reader use the factory default settings. For how to initialize the devices, refer to Section 8. Initializing the System.

7.1. Operation Flow

Use the following procedures to connect the code reader to the PLC for serial communications.



7.4.4. Checking the Receive Data

In the CX-Programmer, check that the correct data is written to the I/O memory of the PLC.

7.2. Code Reader Setup

Set up the code reader.



Precautions for Correct Use

Use a PC (personal computer) to set the parameters for the code reader.

Note that you may need to change the PC settings depending on the condition of your PC.

7.2.1. Setting the Parameters

Set the parameters for the code reader.

Set the IP address of your PC to 192.168.188.101 and its subnet mask to 255.255.0.0.

1 [Using V320-F/V420-F]

Establish a USB connection between the V320/V420 and the PC according the configuration shown on page 7 or page 9.

Once the connection is established, start the procedure from step 4.

* To use V320/V420, you need to install the driver. For how to install the driver, refer to 2-2-3 Connect to WebLink in the MicroHAWK V320-F/V330-F/V420-F/V430-F Series Barcode Reader User Manual (Cat. No. Z432).

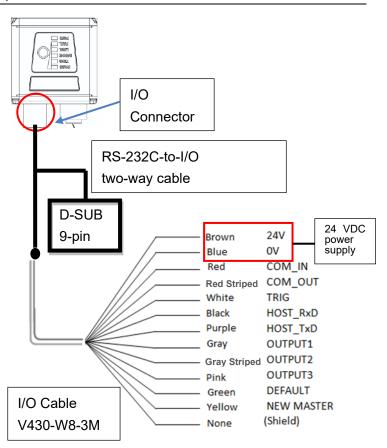
[Using V430-F]

Connect the RS-232C-to-I/O two-way cable V430-WQR-3M to the I/O connector.

Then, connect the I/O connector of V430-WQR-3M to the I/O cable V430-W8-3M.

Connect the 24V and 0V wires of W430-W8-3M to a 24 VDC power supply.

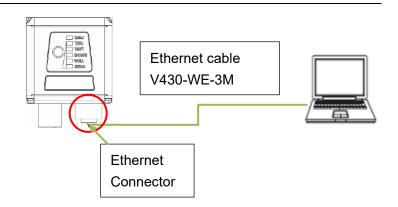
- * In this document, only the power supply wires of the I/O cable are connected and checked. Be careful not to short-circuit any other wires.
- * Ground the shield wire as needed. For more information on grounding, please refer to Grounding in Appendices of the MicroHAWK V320-F/V330-F/V420-F/V430 -F Series Barcode Reader User Manual (Cat. No. Z432).



? [V430-F Series Only]

Connect the Ethernet connector on the code reader to the PC using the Ethernet cable V430-WE-3M.

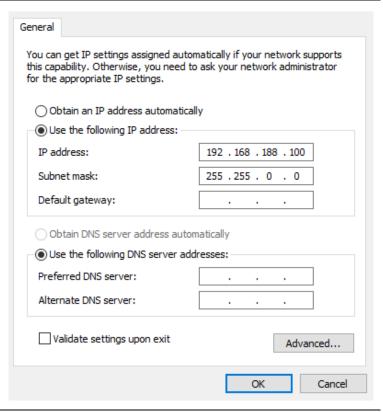
Turn ON the 24 VDC power supply.



3 [V430-F Series Only]

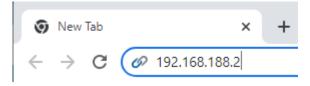
Set the IP Address of the PC. For the IP address, enter 192.168.188.100. For the subnet mask, enter 255.255.0.0.

For how to open the screen shown on the right in Windows 7, please refer to step 4.



- 4 (1) From the Windows Start Menu, select Control Panel Network and Internet Network and Sharing Center.
 - (2) Click on **Local Area Connection**. The Local Area Connection **Status** Dialog Box is displayed. Click **Properties**.
 - (3) In the **Local Area Connection Properties** Dialog Box, select *Internet Protocol Version 4* (*TCP / IPv4*), and click the **Properties** Button.
 - (4) Click the OK Button.
- 5 Start your browser and enter http://192.168.188.2.

"Google Chrome" is the recommended browser.



6 When the WebLink startup screen is displayed, go to step

If you cannot access by WebLink, go to step 7.



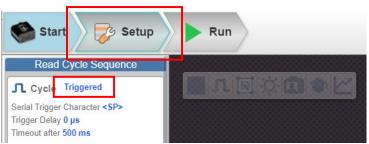
- 7 If the WebLink startup screen does not appear, it means that communications are not established between the code reader and the PC. Please check the following.
 - The code reader and the PC have a proper physical (cable) connection.
 - → Refer to steps 1 and 2 to check the connection.
 - The IP Addresses of the PC and code reader are set correctly.
 - \rightarrow Refer to step 4 to set the IP address of the PC.

For other measures that can be taken, please refer to When unable to access by WebLink in Q&A in Appendices of the MicroHAWK V320-F/V330-F/V420-F/V430-F Series Barcode Reader User Manual (Cat. No. Z432).

A The WebLink screen appears.



O Click on the Setup Tab and, in Read Cycle Sequence, set Cycle to Triggered.



10 Click on the gear icon on the upper right of the screen and select **Advanced**.



The Advanced Settings Screen 11 appears.

> Select the Communications Tab and check that the settings are as follows.

[RS232A]

Baud Rate: 9600 Parity: None Stop Bits: 1 Data Length: 8 [Host Protocol]

Protocol Selection:

Point-to-Point [Preamble]

Preamble: Disabled

Postamble

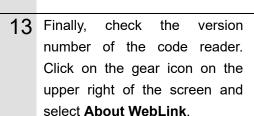
Postamble: Enabled

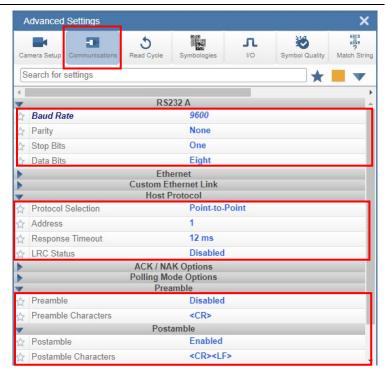
Postamble Characters:

<CR><LF>

12 Click on the icon shown in the red frame to save the settings to

the code reader.









About WebLink is displayed, so you can check the current version of the code reader.

Please update the code reader to the latest version if necessary.

About WebLink

OMRON

OWEBLINK

2.1.0 Patch 4

Reader Model V430-F Serial Number 3838476

Part Number 7412-2000-1005-006
MAC ID 00:0B:43:3A:92:0C
Sensor 1280x960 (SXGA)
Firmware 35-9000097-2.1.1 Alpha 1
Boot 35-9000033-2.0.0 RC 2

Browser Chrome 101.0.4951.54
Operating System Windows 10
Screen Resolution 1920x1040

Contact Us

Done

7.3. PLC Setup

Set up the PLC.

7.3.1. Setting the Hardware

Set the hardware switch on the Serial Communications Unit.



Precautions for Correct Use

Turn OFF the power supply before setting the hardware.

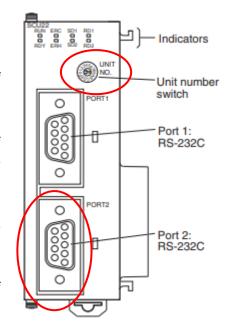
- 1 Confirm that the power supply to the PLC is OFF.
 - * If the power supply is ON, you may not be able to proceed with the subsequent steps of the procedure.

Check the position of the hardware switch on the front of the Serial Communications Unit as shown in the figure on the right.

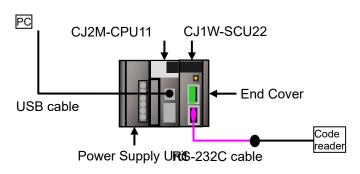
Check the position of the "Port 2" (RS-232C) connector as shown in the figure on the right.

- * It is assumed that "Port 2" of the Serial Communications Unit is used.
- 2 Set the Unit No. switch to "0". (The factory default unit number is "0".)
- Connect the Serial Communications Unit to the PLC, as shown on the right.
 Connect the Serial Communications Unit and the code reader with an RS-232C cable.

Connect the PLC to the PC with a USB cable.

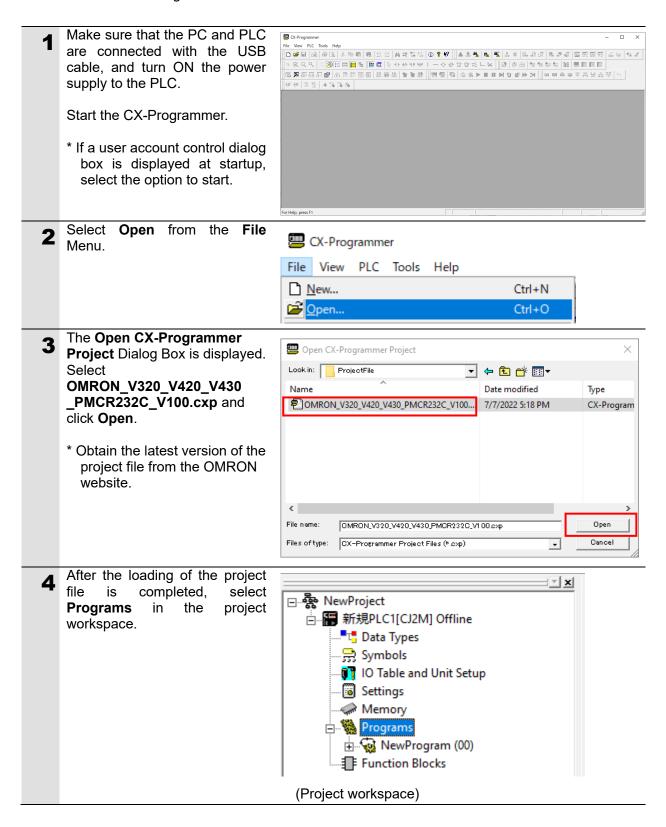


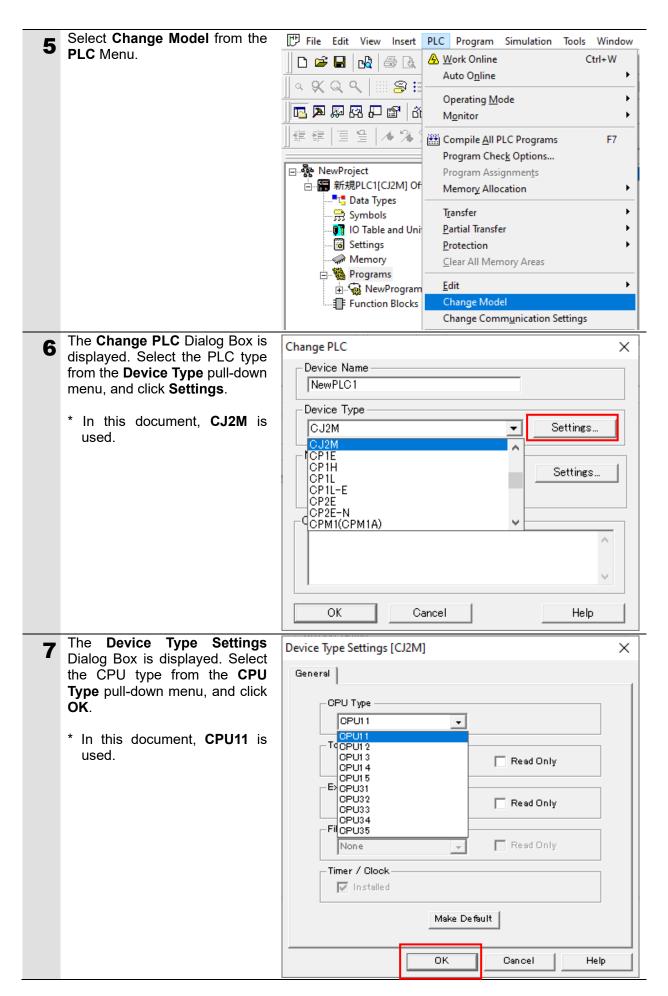


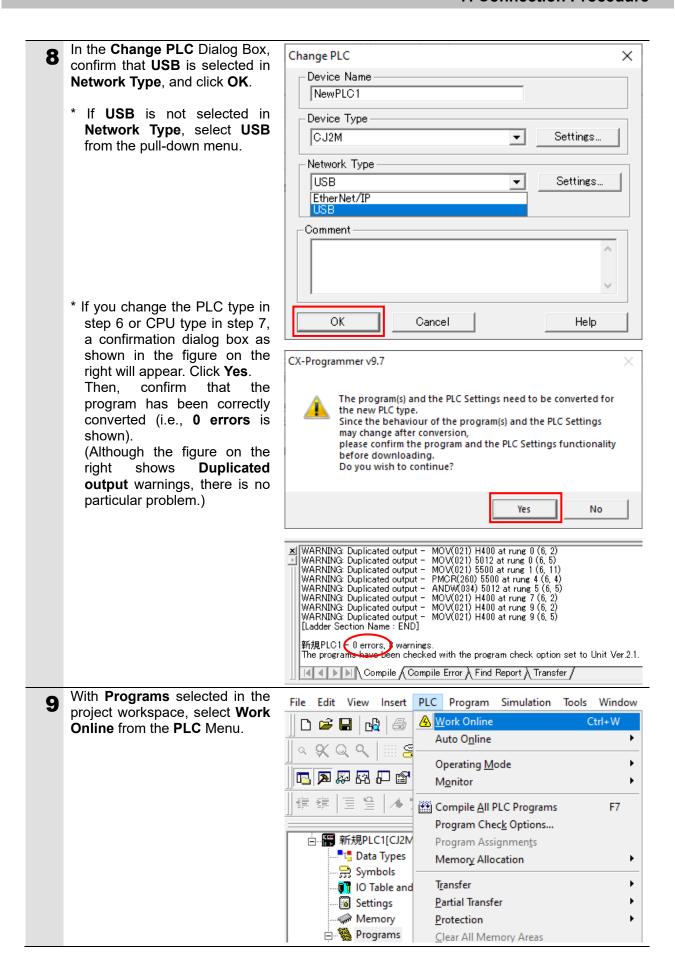


7.3.2. Loading the Project File and Going Online with the PLC

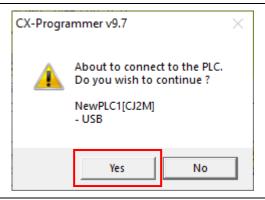
Start the CX-Programmer, load the project file, and go online with the PLC. Install the CX- Programmer and USB driver on the PC beforehand.







A dialog box as shown in the figure on the right appears. Click **Yes**.



Confirm that the CX-Programmer is online with the PLC.







Note

If you cannot go online with the PLC, check the physical cable connections, etc.

If the physical cable connections are correct, return to step 5 and check the settings in steps 6 to 8. For details, refer to the *CX-Programmer Operation Manual* (Cat. No. W446).



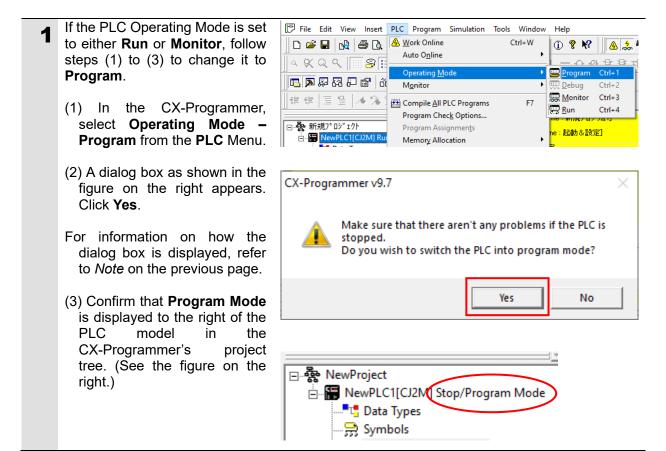
Note

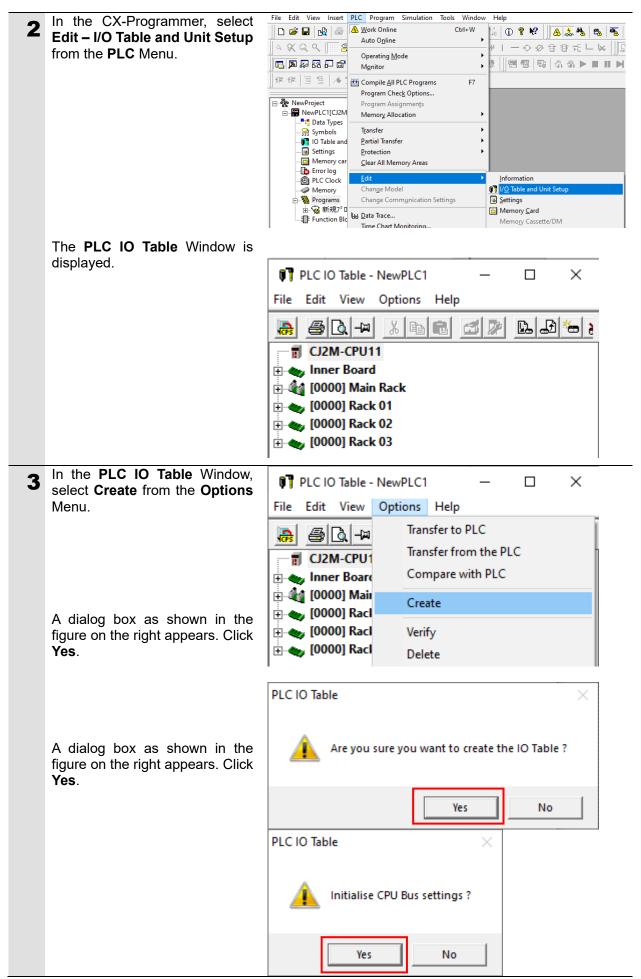
Some of the dialog boxes shown in this document may not be displayed depending on the environment settings of the CX-Programmer. For details on the environment settings of the CX-Programmer, refer to the *CX-Programmer Operation Manual* (Cat. No. W446).

This document assumes that the check box for **Confirm all operations affecting the PLC** is selected.

7.3.3. Creating the I/O Table

Create the I/O table for the PLC.



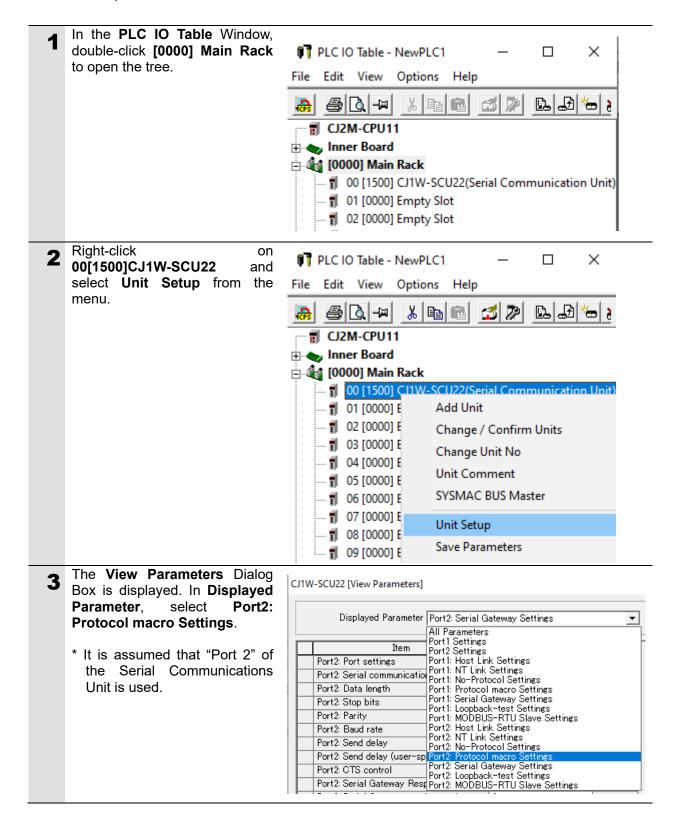


The Transfer from PLC Dialog Transfer from PLC Box is displayed. Select the check boxes for IO Table and Select the transfer target data and press the [Transfer] button. Comment information is deleted if IO Table is transferred. SIO Unit Parameters and click Transfer. ▼ IO Table ▼ SIO Unit Parameters Transfer Cancel Transfer from PLC Transferring... When the transfer is completed, the Transfer Results Dialog Box appears. Check the messages in this dialog box to confirm that the Cancel transfer process is successfully completed. Transfer Results The figure on the right shows **Transfer Success: 1 Unit** <IO Table> Transfer Unsuccessful: 0 Unit. Transfer Success which means I/O table creation <Special Units settings> CPU Bus Unit00: Transfer Success is successfully completed. Transfer Success:1 Unit Transfer Unsuccessful:0 Unit Click OK.

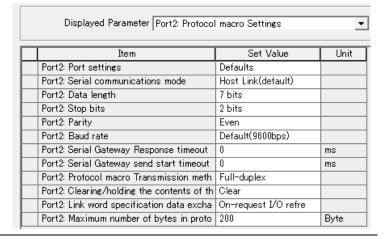
ΟK

7.3.4. Setting the Parameters

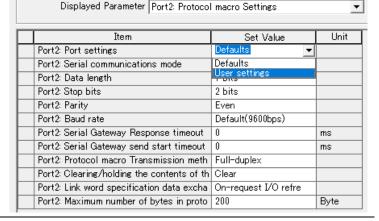
Set the parameters for the Serial Communications Unit.



The settings of Port2: Protocol macro Settings are listed as shown on the right. (The figure on the right shows the default settings.)

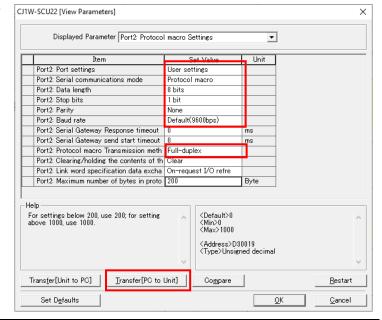


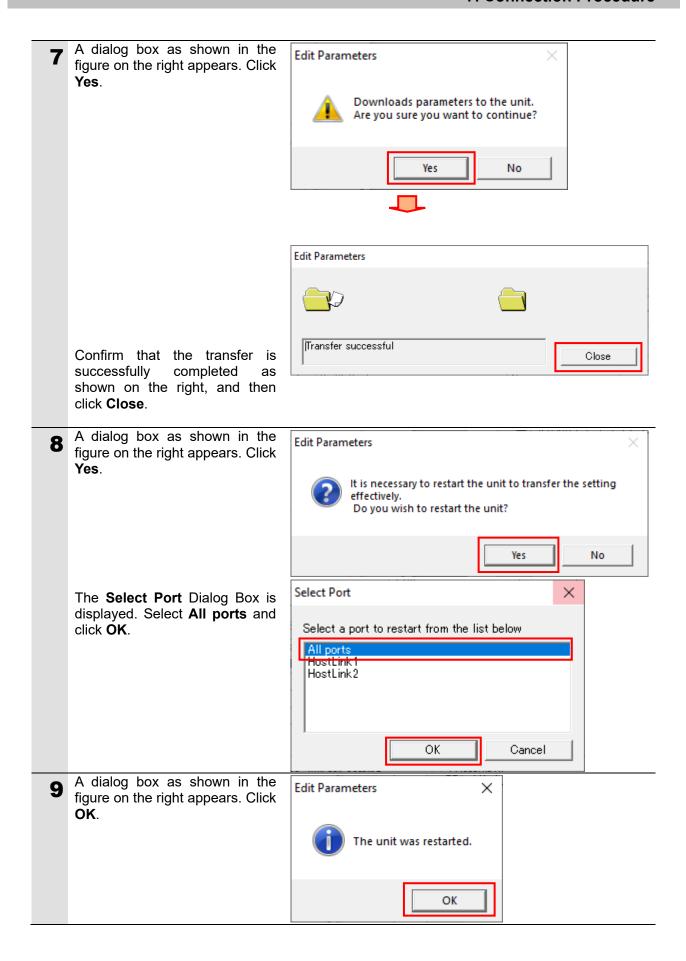
As the set value for Port settings, select User settings.



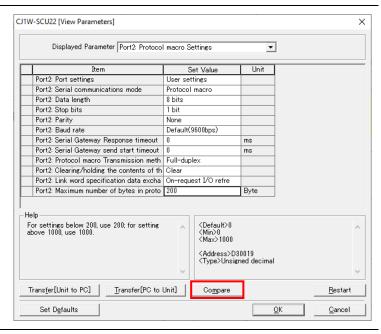
- 6 In the same way as in step 5, set the parameters as follows.
 - Serial communications mode: Protocol macro
 - · Data length: 8 bits
 - Stop bits: 1 bit
 - Parity: None
 - Baud rate: Default (9600bps)
 - Protocol Macro Transmission method:
 Full-duplex
 - * For other parameters, leave the default settings.

Click Transfer [PC to Unit].





10 In the View Parameters Dialog Box, click Compare.

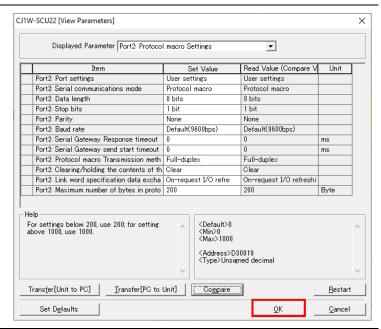


11 Confirm that the comparison is successful as shown on the right, and then click **Close**.



12 In the View Parameters Dialog Box, click OK.

Close the **Edit Parameters**Dialog Box and the **PLC IO Table** Window,



7.3.5. Transferring the Project Data

Transfer the project data to the PLC.

Yes.

In the CX-Programmer, select File Edit View Insert PLC Program Simulation Tools Window 🗋 🗃 🖫 🚱 🎒 Work Online Ctrl+W **Programs** in the project 🍰 🛈 💡 🎋 🔼 🚓 🧆 ங Auto Online workspace, and select Transfer a & Q Q | | | | | | | | | | | 4一一つ必由毎年に14 Operating <u>M</u>ode - To PLC from the PLC Menu. : || B 5 | 5 | 0 4 > ■ | Monitor Monitor 年年 国 9 1 1 F7 Compile All PLC Programs Program Check Options... □ 🦣 NewProject Program Assignments ⊟ ⊞ NewPLC1[CJ2M Memory Allocation ■t Data Types ▶ 🗓 To PLC.. Symbols 👣 IO Table and <u>P</u>artial Transfer From PLC... Ctrl+Shift+T Settings Settings <u>P</u>rotection ▶ <u>C</u>Compare with PLC... Memory car Clear All Memory Areas To File... Error log From File. Edit PLC Clock Memory Change Model Programs Change Communication Settings Select the check boxes for **Download Options** × Program(s), Comments, and Program index, and click the ΟK PLC: NewPLC1 **OK** Button. Include: Cancel 🗹 🥦 Program(s) * Do not select IO table and 🔲 🛅 Settings Special Unit Setup since you □ 👣 IO table Transfer All have set these data in 7.3.3. □ ← Special Unit Setup 🗹 🤮 Symbols and 7.3.4. 🗹 🛅 Comments 🗹 🧰 Program index Comments and Program index may not be shown depending on the PLC model. Symbols, Comments, Program index If so, transfer the project data Transfer To/From: Comment memory Program(s) with only selected. Transfer files of all tasks C Transfer files by the task ✓ Clear program memory Clear automatic allocation area and forced status Exclude Port(HostLink, Peripheral) of PLO Settings from the transfer (Check when transferring CPU unit serial comms port settings changed by NT Link auto-online or CPU unit parameter edit of CX-Integrator) Note: PLC Memory areas(CIO, Timer/Counter, Data memory, etc.) is not transferred. Please transfer PLC Memory areas from the PLC Memory window A dialog box as shown in the CX-Programmer v9.7 figure on the right appears. Click

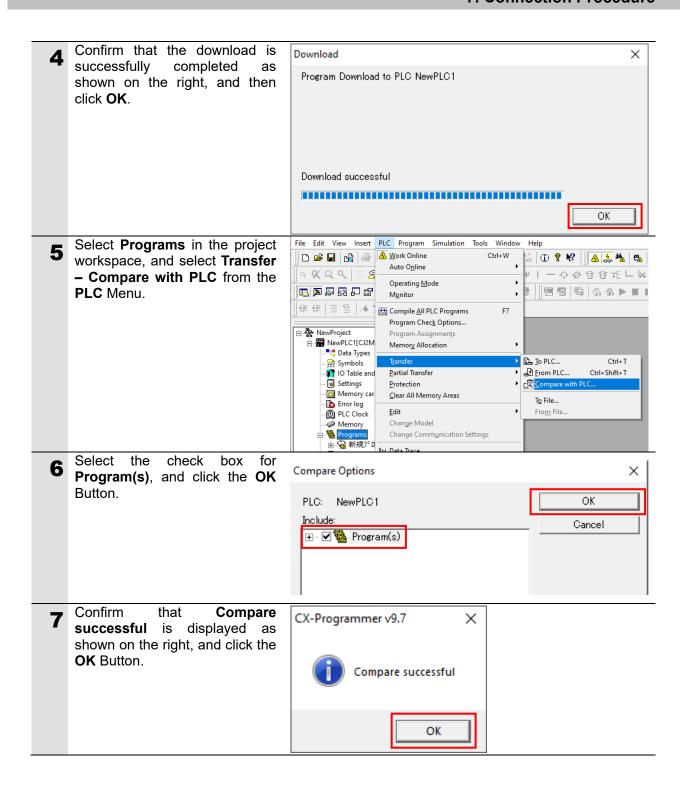
No

This command will affect the state of the connected PLC.

Yes

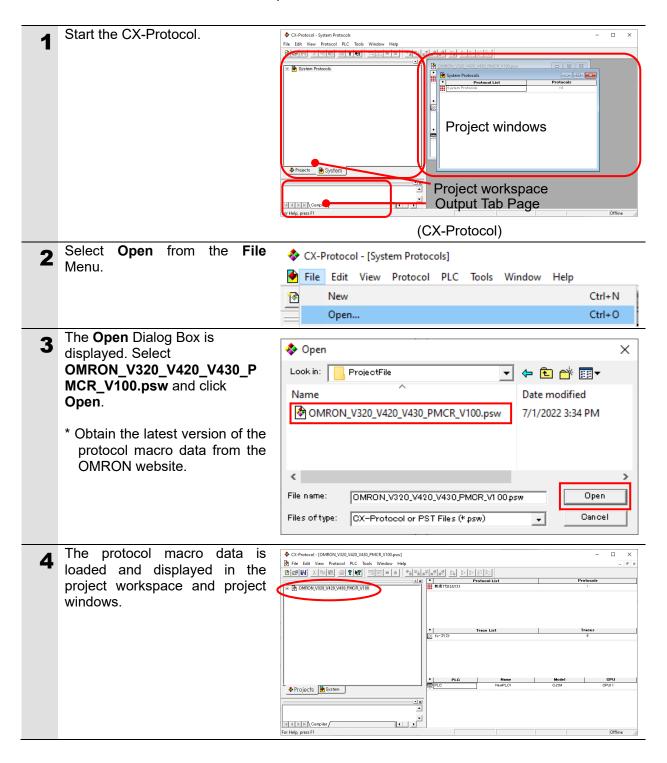
Do you wish to continue?

7. Connection Procedure



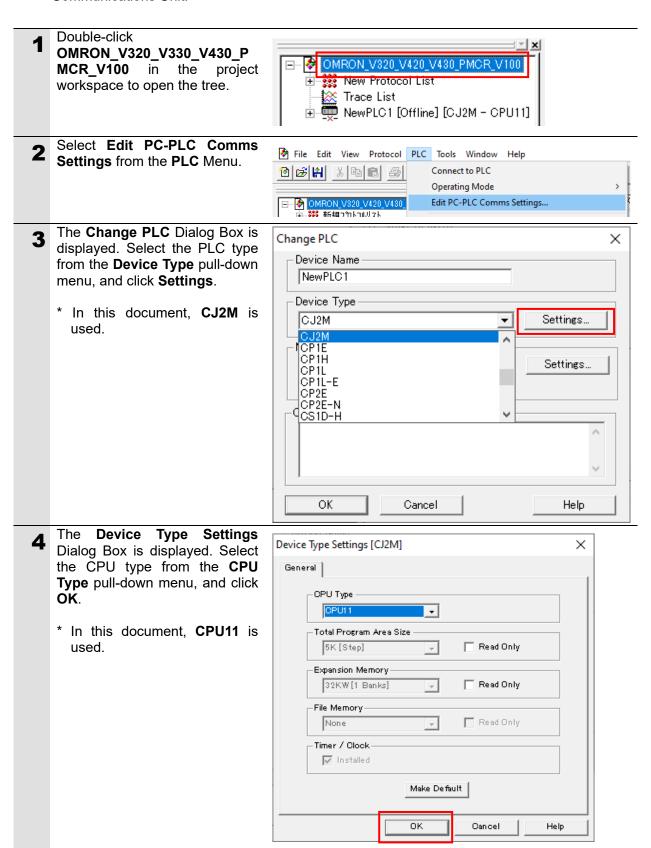
7.3.6. Starting the CX-Protocol and Loading the Protocol Macro Data

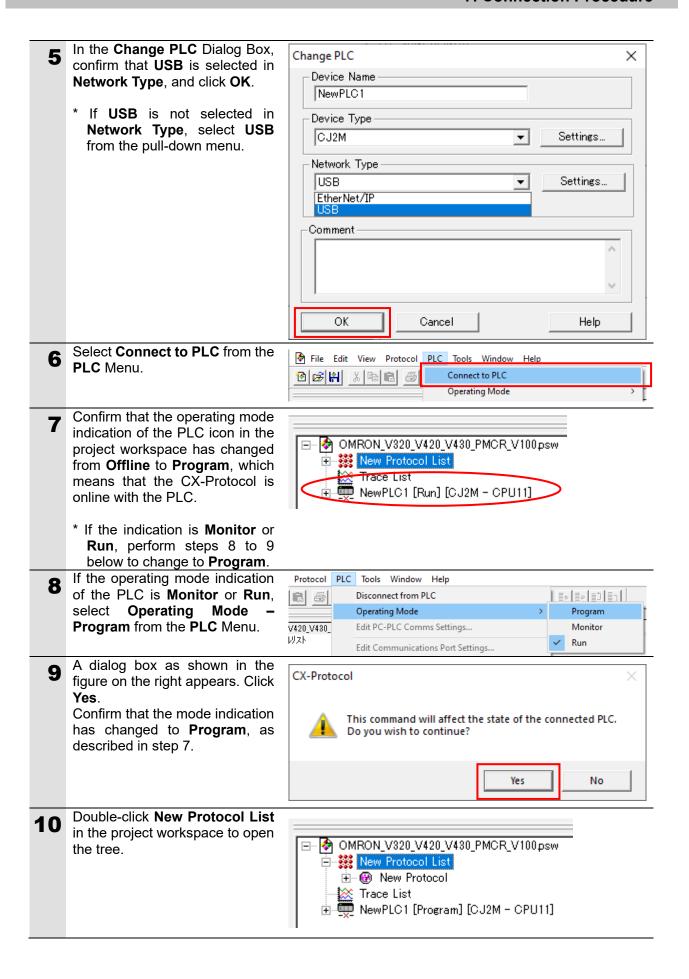
Start the CX-Protocol and load the protocol macro data.

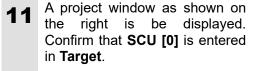


7.3.7. Going Online and Transferring the Protocol Macro Data

Go online with the CX-Protocol and transfer the protocol macro data to the Serial Communications Unit.

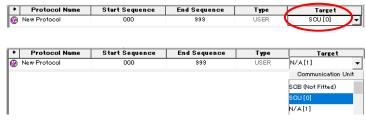


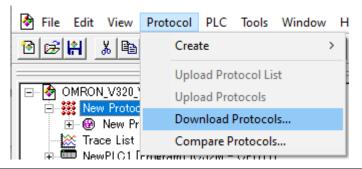




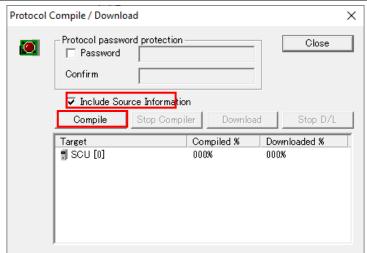
* If **SCU** [0] is not entered, select **SCU** [0] as shown on the right.

With New Protocol List selected, select Download Protocols from the Protocol Menu.



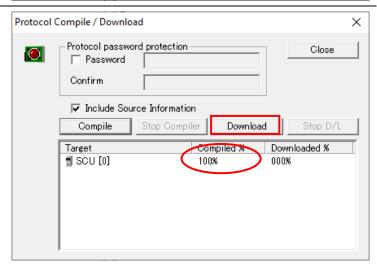


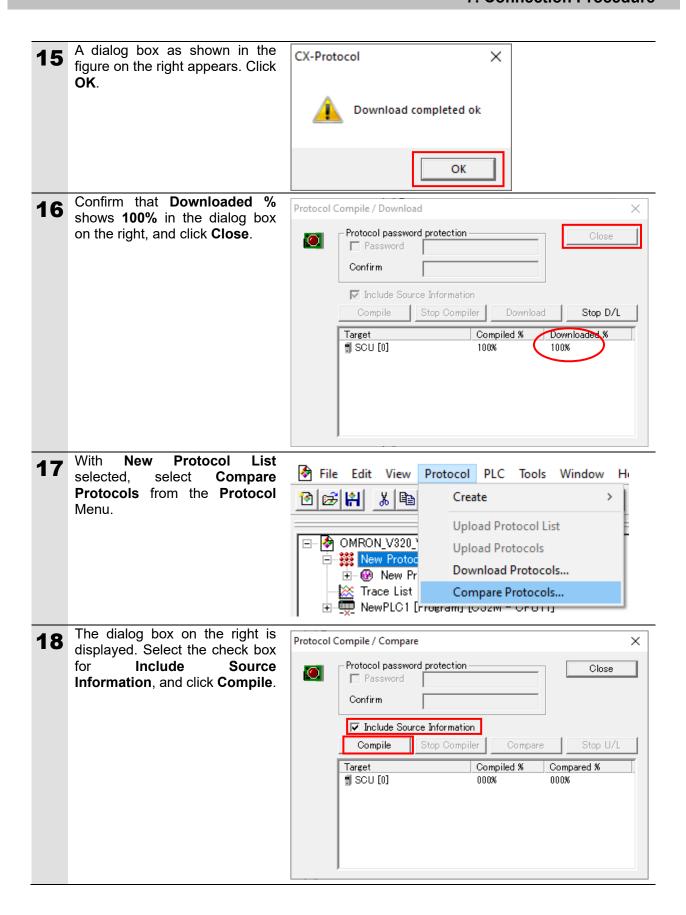
The dialog box on the right is displayed. Select the check box for Include Source Information, and click Compile.



The compile process is complete when Compiled% shows 100% in the dialog box on the right.

Confirm that the compile process is successfully completed as shown on the right, and then click **Download**.





compile process The Protocol Compile / Compare × complete when Compiled% shows 100% in the dialog box Protocol password protection Close Password on the right. Confirm that compile the process is successfully ✓ Include Source Information completed as shown on the Stop Compiler right, and then click Compare. Compile Compare Target Compiled % Compared % ¶ SCU [0] 100% 000% A dialog box as shown in the 20 COMPARE RESULT × figure on the right appears. Click Target Result SCU [0] Successful ΟK Confirm that Compared % 21 Protocol Compile / Compare × shows 100% in the dialog box on the right, and click Close. Protocol password protection Close □ Password Confirm ✓ Include Source Information Stop Compiler Compile Compare Stop U/L Target Compiled % Compared % ¶ SCU [0] 100% 100%

7.4. Checking That Serial Communications Work

Execute the program to check that serial communications work correctly.

⚠ Caution

Sufficiently confirm safety before you perform continuity/current value monitoring in the Ladder Section Window or current value monitoring in the Watch Window. Incorrectly operating shortcut keys to execute force-set/reset or set/reset may cause malfunction of devices connected to Output Units, regardless of the operating mode of the CPU Unit.





Precautions for Correct Use

This document assumes that the code reader is used in the factory default settings. Be sure to initialize the code reader according to 8.2. *Initializing the Code Reader* if it is not in the factory default settings.



Precautions for Correct Use

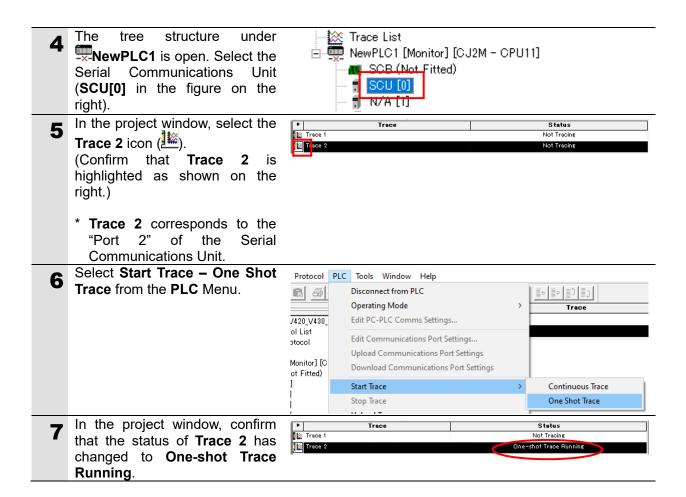
Before performing the following steps, confirm that the RS-232C cable is connected securely. If it is not connected, first turn OFF the power supply to each device and then connect the RS-232C cable.

7.4.1. Starting a Trace

Start a trace in the CX-Protocol.

CX-Protocol, the select Protocol PLC Tools Window Help Operating Mode - Run from Disconnect from PLC the PLC Menu. Operating Mode Program Edit PC-PLC Comms Settings... Monitor /420_V430_ Run Edit Communications Port Settings... stocol A dialog box as shown in the CX-Protocol figure on the right appears. Click Yes. This command will affect the state of the connected PLC. Do you wish to continue? Yes No Confirm that the operating mode OMRON_V320_V420_V430_PMCR_V100psw indication has changed 🖃 🎇 New Protocol List Monitor. double-click and 🛨 🚱 New Protocol NewPLC1. Trace List 🖣 NewPLC 🕻 [Monitor] 🖟 D2M - CPU11]

7. Connection Procedure

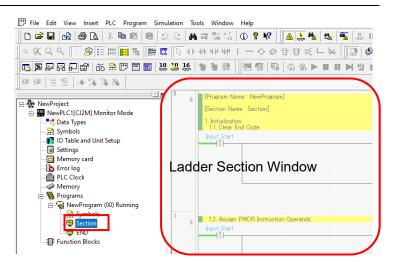


7.4.2. Executing the Program

Execute the program in the CX-Programmer.

1 In the CX-Programmer, open the tree structure under **Programs** in the project workspace, and double-click **Section1**.

In the Ladder Section Window, the ladder diagram for **Section1** is displayed.

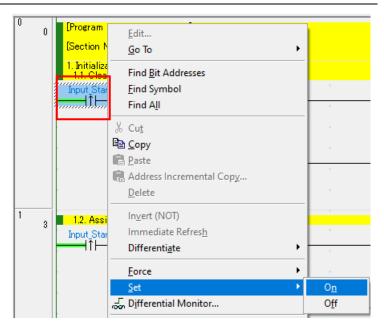


This document uses a barcode as shown in the right figure as an example of reading.

Set the code reader to the position where it can read the barcode in the right figure.



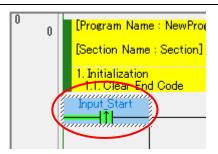
- 3 In the Ladder Section Window, right-click *Input_Start* and select set/reset set from the menu.
 - * Any contact is acceptable as long as it is *Input_Start*. (In the figure on the right, you are operating the *Input_Start* contact in Block 0.)



4 Confirm that the *Input_Start* contact is ON.

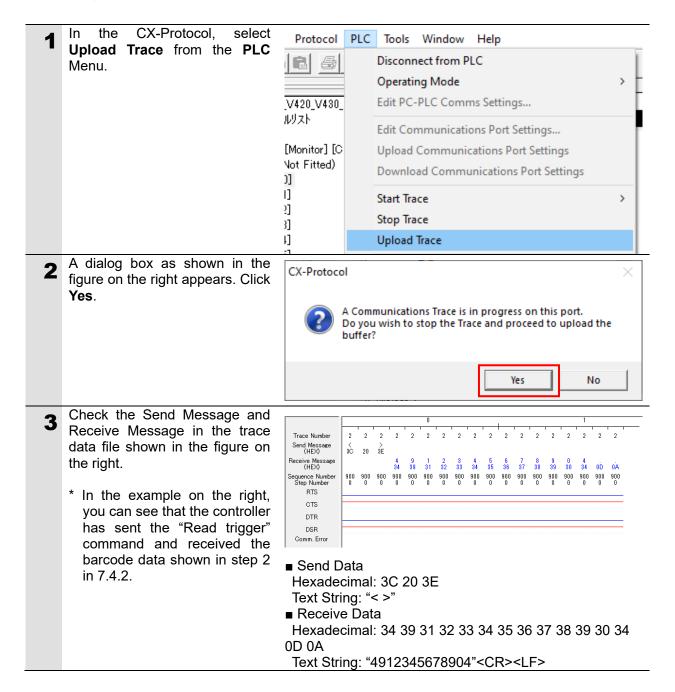
The program starts running and the PLC performs serial communications with the code reader to read the barcode.

* The reading is a successful if the PASS LED indicator on the code reader is lit green.



7.4.3. Checking the Trace Data

Using the trace data of the CX-Protocol, check that the correct data is sent and received.



7.4.4. Checking the Receive Data

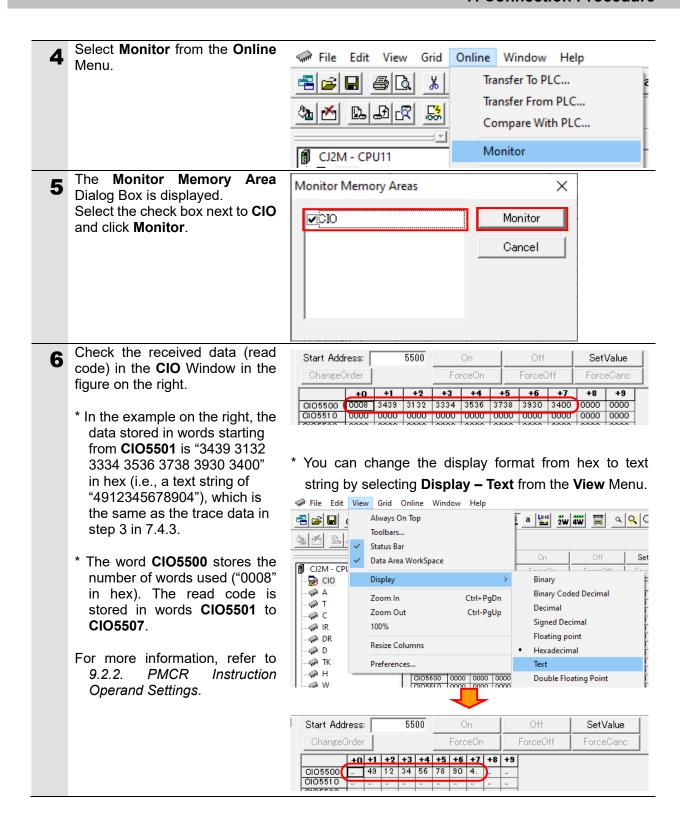
In the CX-Programmer, check that the correct data is written to the I/O memory of the PLC.

In the CX-Programmer, select File Edit View Insert PLC Program Simulation Tools Window 🗅 🚅 🖫 🕍 🚔 🐧 🔼 Work Online Ctrl+W ① ? K? 🔼 🍰 🦓 🙉 📆 😃 Edit - Memory from the PLC Auto Online ۹ 💢 Q ۹ 📗 🥞 🗄 一个必由母在「★ 🔛 🕫 Menu. Operating Mode 🔼 🔊 🕾 🗗 🖆 🐧 Monitor 奪享 国 열 👍 🔭 🖀 Compile <u>A</u>ll PLC Programs Program Check Options... NewProject Program Assignmen<u>t</u>s Memory Allocation 🛂 Data Types Transfer Symbols IO Table and Unit Partial Transfer Settings Protection Memory card
Error log Clear All Memory Areas Information PLC Clock **♥**¶ I/<u>O</u> Table and Unit Setup Memory Programs Change Communication Settings Settings Memory Card யூ Data Trace... Symbols
Section Memory Cassette/DM Time Chart Monitoring... Reset CP1/CP2 Built-in Ethernet Port - END Force Error Log Function Blocks Expan In the PLC Memory Window PLC Memory - NewPLC1 displayed, double-click File View Window Help listed in the **Memory** Tab Page. AM BAR B X 52B CJ2M - CPU11 - M - C 🧼 DR a∰ D ⊸ TK *♠* H ₩ 📥 🧰 E CJ2M - CPU11 Monitor NUM **PLC Memory Window** In the CIO Window displayed, PLC Memory - NewPLC1 - [CIO] × enter 5500 in the Start Address File Edit View Grid Online Window Help _ & × field. Confirm that the start address is **%** M B B B R S → S P B changed to CIO5500. Start Address CJ2M - CPU11 CIO +3 +4 +5 +7 +8 +9 A CI05500 CIO5500 CIO5520 CIO5520 CIO5530 CIO5550 CIO5560 CIO5570 CIO5580 CIO5590 CIO5660 CIO5660 CIO5630 CIO5620 CIO5630 CIO5640 ₩ T - C ⊸ IR n DR *ℯ* D → TK 🧼 Н ₩

CIO5500

CJ2M - CPU11

MUM



8. Initializing the System

In this document, it is assumed that the controller and the code reader use the factory default settings.

If you change their settings from the default, you may not be able to perform various setting procedures as described.

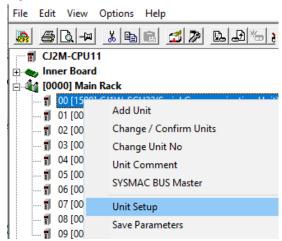
8.1. Initializing the PLC

In order to initialize the PLC, both the CPU Module unit and Serial Communications Unit must be initialized. Please put the PLC in PROGRAM mode before initialization.

8.1.1. Serial Communications Unit

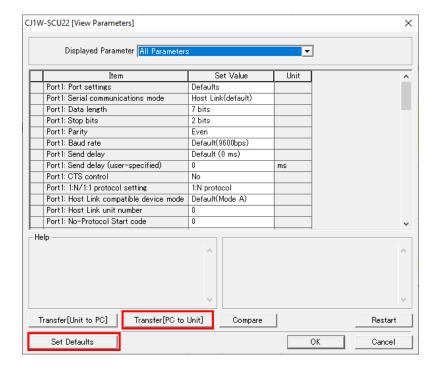
To initialize the Serial Communications Unit, in the CX-Programmer, select **Edit – I/O Table** and **Unit Setup** from the **PLC** Menu.

In the **PLC IO Table** Window, right-click on the Serial Communications Unit and select **Unit Setup** from the menu.



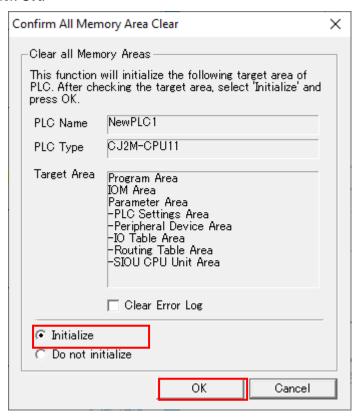
In the View Parameters Dialog Box, after clicking Set Defaults, click Transfer [PC to Unit].

8. Initializing the System



8.1.2. **CPU Unit**

To initialize the CPU Unit, select Clear All Memory Areas from the PLC Menu in the CX-Programmer. In the Confirm All Memory Area Clear Dialog Box, select Initialize and click OK.



8.2. Initializing the Code Reader

For information on initializing the code reader, please refer to *How to initialize the settings?* in Q&A in *Appendices* of the *MicroHAWK V320-F/V330-F/V420-F/V430-F Series Barcode Reader User Manual* (Cat. No. Z432).

9. Program

This section describes the details of the program and protocol macro data used in this document.

9.1. Overview

This section describes the specifications and functions of the program and protocol macro data used to check the connection between the code reader and the PLC (Serial Communications Unit (hereinafter SCU unit)).

This program and protocol macro data use the protocol macro function of the SCU unit to send and receive a "Read trigger" command to and from the code reader, and judge whether they have ended normally or abnormally.

Here, "normal end" of the program means that the communications sequence of the protocol macro has ended successfully.

Also, "error end" means that the communications sequence of a protocol macro has ended abnormally.

In this section, if it is necessary to distinguish between decimal data and hexadecimal data, add "&" to the beginning of decimal data and "#" to the beginning of hexadecimal data. (For example, "&1000" for decimal data, "#03E8" for hexadecimal data)



Note

We have verified in our test configuration that the program and protocol macro data enable communications for the product versions and product lot used for evaluation.

However, we do not guarantee their operations where there are electrical noise or other disturbances, or variations in the performance of the devices themselves.

9.1.1. Communications Data Flow

This is the flow from issuing command data from the PLC (SCU unit) to the code reader through serial communications and receiving response data from the code reader.

Communications Sequence The PROTOCOL MACRO instruction (Mnemonic: **Execution Processing** PMCR) for the sequence number specified in the program is executed to call the communications sequence (protocol macro data) registered in the SCU unit. Command Send Processing Based on the sequence number specified in step 1, the SCU unit issues a send message (command data) to the code reader. Response Receive The SCU unit stores the receive message (response Processing data) received from the code reader in the internal memory of the specified CPU Unit.

9.1.2. PMCR Instruction and Send and Receive Messages

This section describes the PROTOCOL MACRO instruction (Mnemonic: PMCR, hereinafter abbreviated as "PMCR instruction") and the general movement of send and receive messages.



Note

For details, refer to *Serial Communications Instructions (PMCR)* in *Section 3 Instructions* in the *CJ-series Instructions Reference Manual* (Cat. No. W474).

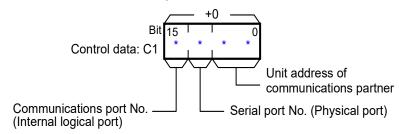
• PMCR Instruction Operand Data

| Instruction | Mnemonic | Code | Symbol/Operand | Function | Location | Execution condition |
|-------------------|---------------|------|--|---|----------|---------------------|
| PROTOCOL MACRO | PMCR @PMCR | 260 | PMCR(260) C1 C2 S R C1: Control word 1 C2: Control word 2 S: 1st send word R: 1st receive word | Calls and executes a communications sequence registered in a Serial Communications Board (CS Series only) or Serial Communications Unit. CPU Unit Serial Communications Unit Port To mumber R m to External device | Output | Required |

C1: Control Data

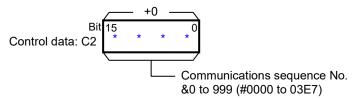
Set three types of data about the SCU unit.

- Communications port No. (Internal logical port): #0 to 7
- Serial port No. (Physical port): #1 to 2 (#1: PORT1, #2: PORT2)
- Unit address of communications partner: #Unit No. + #10



C2: Control Data

Set the communications sequence number registered as protocol macro data. Refer to 9.2.1. Communications Sequence Number for the sequence number registered in the protocol macro data.



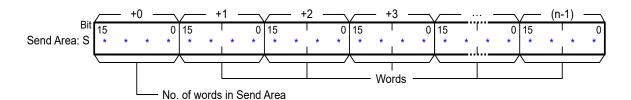
S: First Send Word and Send Area (Send Area Specification)

Set the number of words (n) to be secured for the send area (including the word S).

Setting range: n = &0 to 250 or #0000 to 00FA

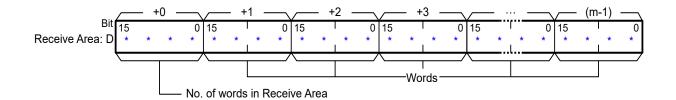
Send data (data assigned to variables) is stored in the words S+1 to S+(n-1).

If there is no operand specified in the execution sequence, such as a direct or linked word, specify the constant #0000 for the word S.



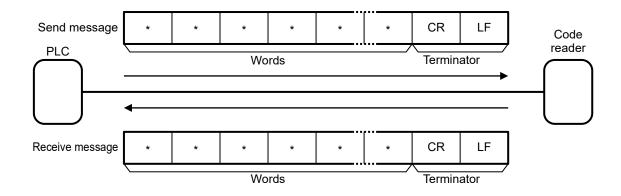
D: First Receive Word and Receive Area (Receive Area Specification)

The number of words (m) of received data is automatically stored in word D (including the word D). In the words D+1 to D+(m-1), actually received data is stored. (Setting range: m = &0 to 250 or #0000 to \$00FA)

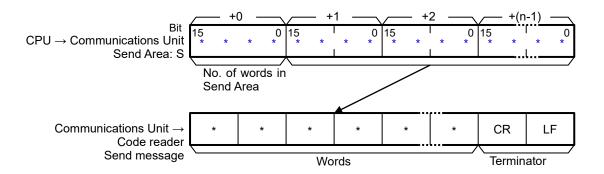


• Send and Receive Messages

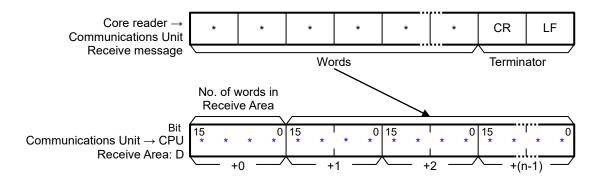
Overview of Send and Receive Messages



Relationship between Send Area S (PMCR Instruction Operand) and Send Message



Relationship between Receive Message and Receive Area D (PMCR Instruction Operand)



9.2. Communications Sequence

This section describes the communications sequence (protocol macro data) that can be used with PMCR instructions in the program.

9.2.1. Communications Sequence Number

The communications sequence (protocol macro data) registered in the SCU unit is identified by the communications sequence number. By specifying the communications sequence number with a PMCR instruction, the corresponding code reader command is executed in the code reader.

The following communication sequence is available with the protocol macro data.

| No. | Command | Description |
|-----|--------------|------------------------------------|
| 900 | Read trigger | Issues a trigger to read the code. |

9.2.2. PMCR Instruction Operand Settings

The PMCR instruction operands for communications sequence No. 900 "Read trigger" are as follows.

Settings of Control Word C1 (C1: 5010)

| Word | Setting (Data format) | Data description |
|------|---------------------------------------|-----------------------------------|
| | Communications port No. (1-digit hex) | |
| 04 | Serial port No. (1-digit hex) | #7210: Communications port No. 7, |
| C1 | Unit address of communications | Serial port No. 2, #Unit No.+ #10 |
| | partner (2-digit hex) | |

Setting of Control Word C2 (C2: 5011)

| Word | Setting (Data format) | Data description |
|------|-----------------------------|---------------------|
| C2 | Communications sequence No. | &900 (Read trigger) |

Setting of First Send Word (S: 5020)

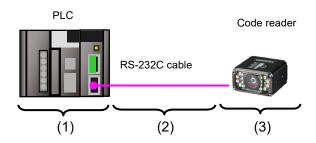
| Word | Setting (Data format) | Data description |
|------|------------------------------------|------------------------------------|
| S | Number of Send words (4-digit hex) | #0000: Specifies that the command |
| | | does not have required parameters. |

Settings of First Receive Word and Area (D: 5500)

| Word | Setting (Data format) | Data description |
|-------|---------------------------------------|-------------------------------------|
| D | Number of Receive words (4-digit hex) | |
| D+1 | Receive word 0 (4-digit hex) | |
| D+2 | Receive word 1 (4-digit hex) | (No setting is required since it is |
| D+3 | Receive word 2 (4-digit hex) | receive data.) |
| : | : | |
| D+250 | Receive word 249 (4-digit hex) | |

9.3. Error Judgment Processing

This program performs error judgment processing for the following three types of errors (1) to (3). Refer to 9.8. Error Processing for error codes.



(1) PMCR instruction execution error (PMCR instruction error)

An error such as a sequence No. setting error or memory word setting error that makes a PMCR instruction inexecutable is judged as a "PMCR instruction error". The judgment is made by the SCU unit's CIO Area addresses 1519.00 to 03 "Port Operation Status Error Codes".

(2) Code reader communications error (Communications error)

An error such as garbled characters in data transmission, transmission error due to inconsistent baud rate setting in communications with the code reader, etc.is judged as a "Communications error". The judgment is made by the SCU unit's CIO Area address 1518.15 "Transmission Error Status Transmission Error Flag".

(3) Code reader error

An error such as a command error, parameter error, data error, or inexecutable error on the code scanner is judged as a "Code reader error". The judgment is made based on the response data returned from the code reader. The program detects this error as a timeout error in (2) since no response is returned from the code reader when it occurs.



Note

For the CIO Area of the SCU unit, refer to 9.4.2. Fixed CIO Area and Related Auxiliary Area Addresses.

9.4. Memory Map

This section describes the memory map of the program.

9.4.1. Usable Memory Addresses

The tables below show area and word addresses that are required to execute the program. You can change the following allocations to any addresses.



Precautions for Correct Use

When you change the address allocations, be careful not to cause address duplication.

• Input Memory

Below is the word addresses in the CIO Area that are used to operate the program.

| Address | Data | Variable name | Description |
|---------|------|---------------|--|
| | type | | |
| 5000.00 | BOOL | Input_Start | Turns from OFF to ON to start the program. |

Output Memory

Below are the word addresses that reflect the execution result of the program.

| Address | Data | Variable name | Description |
|---------|------|--------------------------------|---|
| | type | | |
| 5000.02 | BOOL | Output_NormalEnd | Turns ON when the program has ended normally. |
| 5000.03 | BOOL | Output_ErrorEnd | Turns ON when one or more of the following |
| | | | errors occur. |
| | | | ① PMCR instruction error |
| | | | ② Communication error |
| | | | ③ Code reader error |
| 5501 | WORD | ReadCodeValue | Stores the read code value received from the |
| to 5750 | | | code reader. 250 words are secured. |
| H400 | UINT | Output_ProtocolMacro_ErrorCode | Stores the error code if a PMCR instruction error |
| | | | or communication error occurs. |

• Internal Memory

Below are the word addresses that are used only for calculations by the program.

| Address | Data | Variable name | Description |
|---------|------|--|---|
| | type | | |
| 5000.01 | BOOL | Internal_PMCRInstructionExecuting | Indicates the execution status of the |
| | | | PMCR instruction. |
| | | | Turns ON when the PMCR instruction is |
| | | | executed and turns OFF when not |
| | | | executed. |
| 5000.04 | BOOL | Internal_PMCRInstruction_NormalEnd | Turns ON when the PMCR instruction has |
| | | | ended normally. |
| 5000.05 | BOOL | Internal_PMCRInstruction_ErrorEnd | Turns ON if a communication error |
| | | | (transmission error, etc.) occurs. |
| 5000.07 | BOOL | Internal_ProtocolMacroErrorCodePresent | Turns ON if a PMCR instruction error (one |
| | | | of the following three) occurs. |
| | | | ① Sequence No. Error |
| | | | ② Data Read/Write Area |
| | | | Exceeded Error |
| | | | ③ Protocol Data Syntax Error |
| 5010 | UINT | Internal_ControlData_1 | This is a PMCR instruction execution |
| | | | parameter. |
| 5011 | UINT | Internal_ControlData_2 | This is a PMCR instruction execution |
| | | | parameter. |
| 5012 | UINT | Internal_ProtocolMacro_ErrorCode | Stores the error code if a PMCR |
| | | | instruction error occurs. |
| 5020 | UINT | Internal_SendDataStartWord | Sets the number of send message words |
| | | | for the PMCR instruction. |
| 5500 | UINT | Internal_ReceiveDataStartWord | Stores the number of receive message |
| | | | words from the code reader. |

9.4.2. Fixed CIO Area and Related Auxiliary Area Addresses

The tables below show area addresses that are required to execute the program.

CIO Area

The following address allocations cannot be arbitrarily changed since they are fixed by the unit address (unit number) setting for the SCU unit.

In the program, the unit number is set to "0".

| Address | Data type | Variable name |
|---------|-----------|----------------------------------|
| 1518.15 | BOOL | TransmissionError_SCU_0_P2 |
| 1518 | WORD | TransmissionErrorStatus_SCU_0_P2 |
| 1519.10 | BOOL | SequenceAbout_SCU_0_P2 |
| 1519.11 | BOOL | SequenceEnd_SCU_0_P2 |
| 1519.15 | BOOL | ProtocolMacroExecuting_SCU_0_P2 |
| 1519 | UINT | ProtocolMacroErrorCode_SCU_0_P2 |



Note

For details on the CIO Area of the SCU unit, refer to 2-3-2 CIO Area in 2-3 I/O Memory Allocations in the CJ-series Serial Communications Boards/Units Operation Manual (Cat. No. W336).

• Related Auxiliary Area

The following related Auxiliary Area address allocation cannot be arbitrarily changed because it corresponds to the communications port (internal logical port) specified in the program (by the PMCR instruction operand).

The program uses communications port No. 7 (internal logical port).

| Address | Data type | Variable name |
|---------|-----------|----------------------------------|
| A202.07 | BOOL | CommunicationsPortEnabledFlag_P7 |



Note

For the related Auxiliary Area used for PMCR instructions, refer to *Serial Communications Instructions (PMCR)* in *Section 3 Instructions* in the *CJ-series Instructions Reference Manual* (Cat. No. W474).

9.5. Ladder Program

9.5.1. Functional Components of Ladder Program

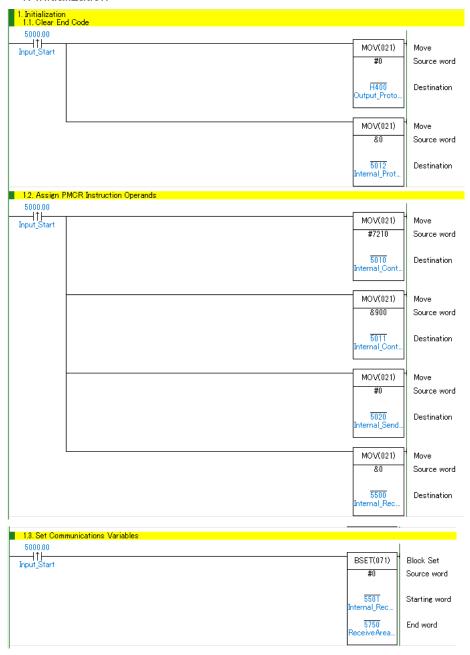
The functional components of the program are as follows.

| Category | Subcategory | Description |
|-------------------|----------------------------|--|
| 1. Initialization | 1.1. Clear End Code | Clear the used area and make initial |
| | 1.2. Assign PMCR | settings as a preparation for |
| | Instruction Operands | communications. |
| | 1.3. Set Communications | |
| | Variables | |
| 2. PMCR | 2.1. PMCR Instruction | Call and execute the communications |
| Instruction | Executing | sequence (protocol macro data) |
| Executing | 2.2. PMCR Instruction | registered in the SCU unit. After |
| Status | Execution Processing | execution, make a normal/error judgment |
| Control | 2.3. Normal/Error Judgment | based on related flags and receive data. |
| | Processing | |
| 3: Normal End | 3.1. Normal End | Turn ON the Normal End Flag. |
| Status | Processing | Set the end code for normal end. |
| Control | 3.2. Set End Code | |
| 4: Error End | 4.1: Error End Processing | Turns ON the Error End Flag. |
| Status | 4.2. Set End Code | Set the end code corresponding to the |
| Control | | error cause. |

9.5.2. Detailed Description of Functional Components

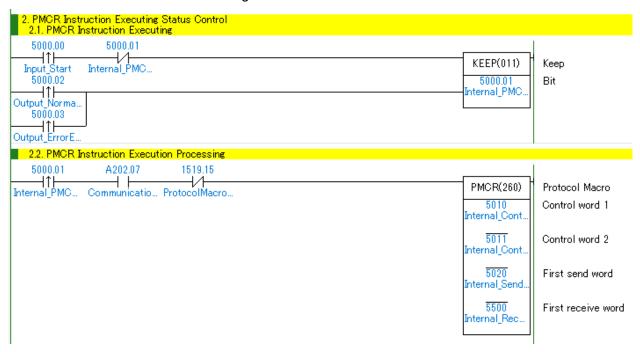
The functional components of the program are shown below.

• 1. Initialization



| No. | Overview | Description | |
|------|-------------------------|--|--|
| 1.1. | Clear End Code | Clears the error code storage area to zeros. | |
| 1.2. | Assign PMCR Instruction | Sets the execution parameters (operands) of the PMCR | |
| | Operands | instruction. | |
| 1.3. | Set Communications | Initializes the storage area for the receive data. | |
| | Variables | | |

• 2. PMCR Instruction Executing Status Control



| No. | Overview | Description | |
|------|----------------------|---|--|
| 2.1. | PMCR Instruction | Changes to the PMCR Instruction Executing status. | |
| | Executing | The executing status is cleared at the normal/error end | |
| | | of the program. | |
| 2.2. | PMCR Instruction | Executes the PMCR instruction on condition that | |
| | Execution Processing | communications port No. 7 is usable and that the | |
| | | protocol macro is not running. | |



Precautions for Safe Use

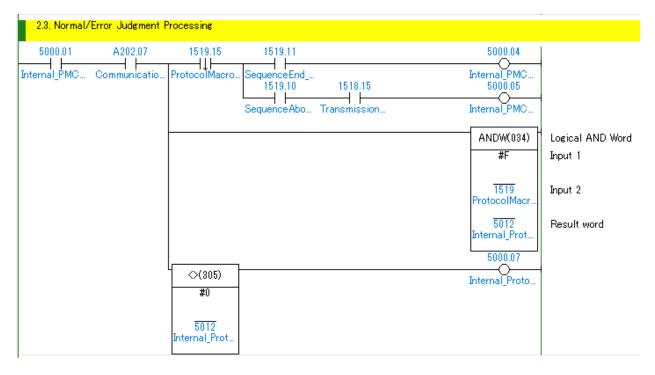
Check the customer specifications of the program before specifying the receive data storage area in the PMCR instruction. An unexpected memory area may be overwritten.



Precautions for Correct Use

The program uses communications port No. 7 (internal logical port).

Even when a communication port is necessary for other communications, avoid using communications port No. 7. If you must use communications port No. 7, confirm that the Network Communications Instruction Enabled Flag (A202.07) is ON before use.



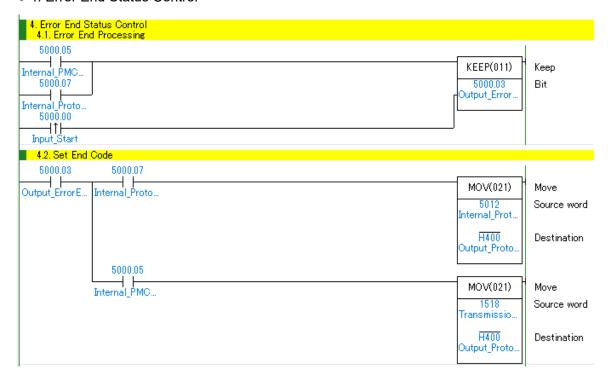
| No. | Overview | | Description |
|------|--------------|----------|---|
| 2.3. | Normal/Error | Judgment | Judges whether program execution has ended normally |
| | Processing | | or abnormally. |
| | | | The program is considered to have ended normally if all |
| | | | of the following conditions are met. |
| | | | (1) PMCR instruction at normal end (without PMCR |
| | | | instruction error) |
| | | | (2) Communications sequence at normal end (without |
| | | | communications error) |
| | | | If an error occurs in either one of the above conditions, |
| | | | the error flag corresponding to the error turns ON. |

• 3. Normal End Status Control



| No. | Overview | Description | |
|------|-----------------------|---|--|
| 3.1. | Normal End Processing | Turns ON the normal end flag when the program is | |
| | | judged to have ended normally in 2.3. Normal/Error | |
| | | Judgment Processing, | |
| 3.2. | Set End Code | Sets the end code for normal end "#0000" in the end | |
| | | code storage area. | |

• 4. Error End Status Control



| No. | Overview | Description | |
|------|---|--|--|
| 4.1. | Error End Processing Turns ON the Error End Flag when the program | | |
| | | judged to have ended abnormally in 2.3. Normal/Error | |
| | | Judgment Processing. | |
| 4.2. | Set End Code | Sets the end code for error end corresponding to the | |
| | | error cause in the end code storage area. | |



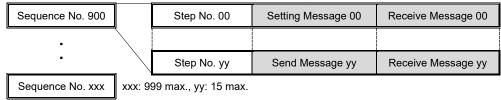
Note

For the end codes, refer to 9.8. Error Processing.

9.6. Protocol Macro Data

Protocol macro data consists of the following components: Sequence, Step, Send Message, Receive Message, and "Reception Matrix".

- When there is only one receive message format for one step (i.e., single send and receive operation)
 - One receive message and one send message are set for the step.



- When there are more than receive messages for one step (i.e., single send and receive operation)
 - One send message and one reception matrix are set for the step.
 - · Several "cases" (receive messages) are set for the reception matrix.

| Sequence No. 900 | | Step No. 00 | Setting Message 00 | Recep | tion Matrix |
|------------------|---------|--------------------------|--------------------|------------------|-----------------|
| | | | | Case No. 00 | Receive Message |
| • | | Step No. yy | | | |
| • | • | yy: 15 max., zz: 14 max. | Case No. zz | Receive Message: | |
| | | yy. 13 max., 22. 14 | illax. | Case No. 22 | ZZ |
| Sequence No. xxx | xxx: 99 | 99 max., Case No. 15 | automatically set | Case No. 15 | Other |

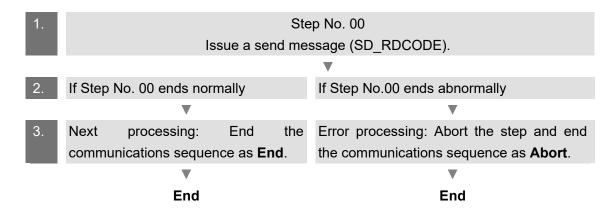
9.6.1. Format of This Protocol Macro Data

This protocol macro data has a structure without the reception matrix as shown below, since it has only one receive message (SD_RDCODE) for one send message (SD_RDCODE). For more information, refer to 9.6.6. Setting the Receive Message.

| Sequence No. 900 | Step No. 00 | SD_RDCODE | RV_RDCODE |
|------------------|-------------|-----------|-----------|
| | | | |

9.6.2. Protocol Macro Processing Procedure

The protocol macro processing procedure is as follows.



9.6.3. Sequence Settings

The protocol macro data uses a "Read trigger" (Communications sequence No. 900) to read the code. The setting items for the communications sequence include **Timeout**.



Note

For details on the sequence settings, refer to 3-2 Sequence Attributes (Common to All Steps) in the CX-Protocol Operation Manual (Cat. No. W344).

• Timeout Settings

The timeout settings (**Timer Tr**, **Timer Tfr**, and **Timer Tfs**) for the sequence are as follows.

Communications Sequence Setting Screen



Settings

| Item | Description | Meaning | |
|---------------------------------|--|---|--|
| Timer Tr | Reception Wait Monitoring | Monitors the time until the code reader receives the first data (header) after it enters the receive wait state in each step in the sequence. | |
| | Time | In the protocol macro data, it is set to 3 seconds. | |
| Timer fr | Timer fr Receive Completed Monitoring Time Time Receive Completed Monitors the time until the code reader completes the reafter it receives the first data (header) in each step sequence. In the protocol macro data, it is set to 3 seconds. | | |
| Send Completed Monitoring after | | Monitors the time until the code reader receives the last data after it sends the header. In the protocol macro data, it is set to 3 seconds. | |



Note

For details on how to calculate the monitoring time, refer to 4-5 Calculation Method of Monitoring Time in the CX-Protocol Operation Manual (Cat. No. W344).

9.6.4. Step Settings

The step settings for communications sequence No.900 are shown below. The step settings include **Retry**, **Send Message** and **Recv Message** (message names), **Next**, and **Error**. The sequence in the protocol macro data consists of Step No. 00 only.



Note

For details on the step settings, refer to 3-3 Step Attributes in the CX-Protocol Operation Manual (Cat. No. W344).

Retry Count Setting

The **Retry** setting for the step is shown below. If an error occurs, the protocol macro will retry the step the specified number of times (0 to 9 times). If the error persists even after the retries, it will go to Error Processing.

The retry count is valid only for the Send & Receive command.

Step Setting Screen



Settings

| Step | Retry |
|------|-------|
| 00 | 3 |

Send/Receive Message (Message Name) Settings

The **Send Message** and **Recv Message** settings for the step are shown below. The send message name and receive message name that are separately registered are set.

Step Setting Screen



Settings

| Step | Send Message | Recv Message | |
|------|--------------|--------------|--|
| 00 | SD_RDCODE | RV_RDCODE | |

Next Processing and Error Processing Settings

The **Next** and **Error** processing settings for the step are shown below. The **Next** processing setting will be executed when the step execution ends normally. The **Error** processing setting will be executed when a communication error occurs.

Step Setting Screen



Settings

| Step | Next | Error |
|------|------|-------|
| 00 | End | Abort |

Processing Items

| Processing | Description | |
|------------------|--|--|
| End | Ends the communications sequence. | |
| Next | Advances to the next step No. | |
| Abort | Aborts the step and end the communications sequence. | |
| Goto | Jumps to the specified step No. | |
| Reception Matrix | Executes the processing specified by the reception | |
| | matrix setting. | |

9.6.5. Send Message Settings

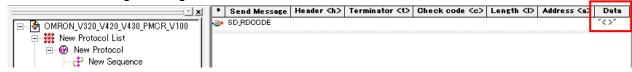
The send message settings are shown below.



Note

For details on the Send Message settings, refer to 3-4 Communication Message Attributes in the CX-Protocol Operation Manual (Cat. No. W344).

Send Message Setting Screen



• Settings for Send Message "SD_RDCODE"

Settings

| No. | Code | Description | |
|-----|-------|---|--|
| (1) | "< >" | Message data: ASCII constant, Data: "< >" | |

Send Message Command Format

This is the command format of messages sent from the SCU unit to the code reader according to the "SD RDCODE" setting.

| Command | Number of | Description | |
|------------|-----------|---|--|
| | bytes | | |
| Header | 0 | None | |
| "< >" | 3 | Fixed: "< >" (#3C203E) (Read trigger command) | |
| Terminator | 0 | None | |

^{*} A setting that is referred to as "Footer" on the code reader corresponds to "Terminator" in the protocol macro data. Hereinafter, it is referred to as "Terminator".

9.6.6. Receive Message Settings

The receive message settings are shown below.



Note

For details on receive message settings, refer to *3-4 Communication Message Attributes* in the *CX-Protocol Operation Manual* (Cat. No. W344).

Receive Message Setting Screen



Settings for Receive Message "RV_RDCODE"
 Settings

(W(1),*)+<t>(2)

| No. | Code | Description | | | |
|-----|---------------------|--|--|--|--|
| (1) | (W(1),*) | Message data: Variable | | | |
| | | Loads all variable length data and stores them in the | | | |
| | | Internal_ReceiveDataStartWord+1 and higher words | | | |
| | | specified by the PMCR instruction operand in the program | | | |
| | | (words starting from 5501). | | | |
| (2) | <t>(Terminator)</t> | Message data: Constant in hex, Type: Code, Data: | | | |
| | | <cr><lf></lf></cr> | | | |

^{*} Header <h> is set to None.

Response Format of Receive Message

This is the response format of the receive message from the code reader that the SCU unit receives according to the RV_RDCODE setting.

| ReadCodeValue | <cr><lf></lf></cr> |
|---------------|--------------------|
|---------------|--------------------|

| Command | Number of | Remarks | |
|------------|-----------|-----------------------------------|--|
| | bytes | | |
| Data | Variable | Variable: ReadCodeValue | |
| | length | | |
| Terminator | 2 | Fixed: <cr><lf> (#0D0A)</lf></cr> | |

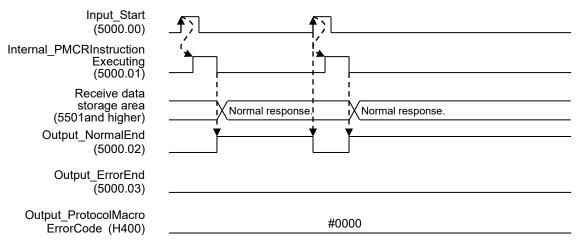
9.7. Timing Chart

The timing chart for the program is shown below.

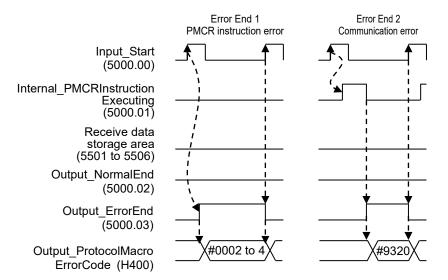
The timing chart patterns are defined as follows.

| Pattern | Normal End | Error End 1 ExecPMCR Instruction Error | Error End 2 Protocol Macro Error | |
|-------------|------------|--|-------------------------------------|--|
| Command | Normal | Error | Error | |
| Code reader | Normal | Normal or Error | Normal or Error | |
| Response | Yes | No | No | |

Normal End



• Error End



9.8. Error Processing

This section provides information on errors that can occur during the execution of the program.

9.8.1. Protocol Macro Error Codes

These errors are detected by the macro operation monitoring function of the SCU unit. They are stored in the word H400 (Variable name: *Output_ProtocolMacro_ErrorCode*).

Error Code List

| Error code | Name |
|------------|-------------------------------------|
| #0000 | No error |
| #0002 | Sequence number error |
| #0003 | Data read/write area exceeded error |
| #0004 | Protocol Data Syntax Error |



Note

For details on protocol macro errors and corrections, refer to 12-3 Troubleshooting in the CJ-series Serial Communications Boards/Units Operation Manual (Cat. No. W336).

9.8.2. Transmission Error Status

The table below shows the error flags for transmission errors that can occur.

They are stored in the word H400 (Variable name: Output_ProtocolMacro_ErrorCode).

Transmission Error Status

| Bit | Description |
|---------|--|
| 15 | 1: Transmission error 0: No transmission error |
| 14 | 1: Send finished monitoring time over 0: Normal |
| 13 | 1: Receive finished monitoring time over 0: Normal |
| 12 | 1: Receive wait monitoring time exceeded 0: Normal |
| 8 to 11 | Number of retries |
| 7 | 1: FCS check error 0: Normal |
| 6 | 1: Commands error 0: Normal |
| 5 | 1: Timeout 0: Normal |
| 4 | 1: Overrun error 0: Normal |
| 3 | 1: Framing error 0: Normal |
| 2 | 1: Parity error 0: Normal |
| 0, 1 | (Not used) |



Note

For details on the transmission error status and corrections, refer to 12-3 Troubleshooting in the CJ-series Serial Communications Boards/Units Operation Manual (Cat. No. W336).

10. Revision History

| Revision | Revision Date | Revised Page and Reason | |
|----------|---------------|-------------------------|--|
| Code | | | |
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