Multi-turn Absolute Rotary Encoder

CSM_E6C-N_DS_E_7_1

Multi-turn Absolute Rotary Encoder

- External diameter of 50 mm.
- Resolution: Single turn: 500 divisions, Multi-turn: -128 to 127 turns
- Easy origin alignment using origin reset function when building into equipment.
- Need for backup power supply eliminated by multi-turn data storage function.
- Product lineup includes both Solid-shaft and Hollow-shaft Models.



Be sure to read *Safety Precautions* on page 4.

Ordering Information

Encoders [Refer to Dimensions on page 5.]

Shaft	Connection method	Model
Shaft model	Pre-wired Model	E6C-NN5C 2M
Shaft model	Pre-wired Connector Model	E6C-NN5C-C 2M
Hollow shaft	Pre-wired Model	E6C-NN5CA 2M
Hollow shaft	Pre-wired Connector Model	E6C-NN5CA-C 2M

Accessories (Order Separately)

[Dimensions: Refer to Accessories for dimensions.]

Name	Model	Remarks	
	E69-C06B		
Couplings	E69-C68B	Different end diameter	
Couplings	E69-C610B	Different end diameter	
	E69-C06M	Metal construction	
	E69-FCA		
Flanges	E69-FCA02	Servo Mounting Bracket E69-2 Servo Mounting Bracket pro- vided.	
Servo Mounting Bracket	E69-2	Three brackets in a set.	

Refer to Accessories for details.

Ratings and Specifications

Model Item		E6C-NN5C E6C-NN5C-C E6C-NN5CA E6C-NN5CA-C					
Power sup	ply voltage	12 VDC -10% to 24 VDC +10%, ripple (p-p): 5% max.					
Current co	nsumption*1	80 mA max.					
Resolu-	Single-turn absolute	500 divisions					
tion	Multi-turn absolute	-128 to 127 turns*2, *3					
Rotational power failu	limitation at re	±80°*4					
	Output code	Binary					
	Alarm output	Counter overflow output*5					
	Output configuration	NPN open-collector output					
Output	Output capacity	Applied voltage: 30 VDC max. Sink current: 10 mA max. (counter overflow output: 30 mA) Residual voltage: 0.4 V max.					
	Logic	Negative logic					
	Direction	Code increases for CW (when viewed	from end of shaft)				
	Input signals	Single-turn data reset, multi-turn data reset*6					
Input	Input current	1 mA max.					
mput	Input logic	Low active, normally open					
	Input time	100 ms min.					
Maximum response frequency		12.5 kHz					
Rise and fall times of output		1 μs max.*7					
Starting to	rque	2.9 mN·m max.					
Moment of	inertia	$1.5 \times 10^{-6} \text{ kg} \cdot \text{m}^2 \text{ max}.$					
Shaft	Radial	30 N					
loading	Thrust	20 N					
Maximum p speed	permissible	1,500 r/min					
Ambient te	mperature range	Operating: -10 to 55°C (with no icing),	Storage: -25 to 65°C (with no icing) *8				
Ambient hu	umidity range	Operating/Storage: 35% to 85% (with	no condensation)				
Insulation I	resistance	20 M Ω min. (at 500 VDC) between current-carrying parts and case					
Dielectric s	trength	500 VAC, 50/60 Hz for 1 min between current-carrying parts and case					
Vibration re	esistance	Destruction: 10 to 500 Hz, 150 m/s² or 2-mm double amplitude for 11 min times each in X, Y, and Z directions					
Shock resis	Destruction: 1,000 m/s ² 3 times each in X, Y, and Z direction		n X, Y, and Z directions				
Degree of protection		IEC 60529 IP50					
Connection method F		Pre-wired Models (Standard cable length: 2 m)	Connector Models (Standard cable length: 2 m)				
Material		Case: ABS, Main unit: PPS, Pressboard panel: SUS304, Shaft: SUS420J2					
Weight (pa	Veight (packed state) Approx. 400 g						
Accessorie	s	Instruction manual Note: Coupling, mounting bracket and hex-head spanner are sold separately					

Note: The data outputs will all turn OFF as soon as the main power supply turns OFF. Data is not saved. *1. An inrush current of approximately 8 A will flow for approximately 6.5 ms when the power is turned ON. *2. Negative values for multi-turn absolute values are express as two's complements (see code at right).

*3. Multi-turn data will change approximately 10 µs after single-turn data. Allow for this when reading data.



- *4. When the power supply is interrupted, multi-turn detection is not performed and multi-turn data is compensated by comparison to the data that existed before the power supply was interrupted. If a rotation operation exceeding $\pm 80^{\circ}$ is performed from the position when the main power supply turns OFF, correct multi-turn data will be lost. The
- application must be set up so that no rotation operations are performed that exceed this stipulation. *5. Output when the multi-turn counter exceeds the -128 to 127 counting range. This error flag will be reset if the count data returns to within the counting range.
- *6. The single-turn data and multi-turn data reset signals can be input independently to reset the single-turn data to address 0 and the multi-turn data to 0 rotations.
- *7. Use an Encoder cable length of 10 m max. When using a cable of 10 m or less, read the code 10 μ s or more after the LSB (2°) of the code changes. *8. The device coupled to the Encoder shaft must also satisfy the ambient temperature condition.

Multi-turn absolute value code

Multi-turn absolute value	Code
10	00001010
9	00001001
8	00001000
7	00000111
6	00000110
5	00000101
4	00000100
3	00000011
2	0000010
1	00000001
0	00000000
-1	11111111
-2	11111110
-3	11111101
-4	11111100
-5	11111011
-6	11111010
-7	11111001
-8	11111000
-9	11110111
-10	11110110
-11	11110101

The expressions for negative values given above can be achieved by reversing 1's and 0's and then adding 1.

I/O Circuit Diagrams



Connections E6C-NN5C(A)

Wire color: grey					Wire color: Black			
Sig- nal	Meaning		Color		Sig- nal Meanin		ng	
ABS0		2 ⁰	Bro	wn	TKN0		2 ⁰	
ABS1		2 ¹	Orar	nge	TKN1		2 ¹	
ABS2		2 ²	Yell	ow	TKN2	Multi-	2 ²	
ABS3	Single-	2 ³	Gre	en	TKN3	turn ab-	2 ³	
ABS4	turn ab-	2 ⁴	Blu	ie	TKN4	solute	2 ⁴	
ABS5	solute data	25	Pur	ple	TKN5	data	25	
ABS6		2 ⁶	Gra	ay	TKN6		2 ⁶	
ABS7		27	Wh	ite	TKN7		27	
ABS8		2 ⁸	Pir	ık	COF	Counter overflow a	larm	
ARST	Single-turn data reset		Lig blu	ht Ie	TRST	Multi-turn reset	data	
GND	0 V*		Bla	ck	GND	0 V*		
Vcc	12 to 24 VDC*		Re	d	Vcc	12 to 24 VDC*		
SHIELD	IELD Shield			-	SHIELD	Shield		

Connections E6C-NN5C(A)-C

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Pin No.	Sig- nal	Meaning		Pin No.	Sig- nal	Meani	ng
A1	ABS0		2 ⁰	B1	TKN0		2 ⁰
A2	ABS1		2 ¹	B2	TKN1		2 ¹
A3	ABS2		2 ²	B3	TKN2	Multi-	2 ²
A4	ABS3	Single-	2 ³	B4	TKN3	turn	2 ³
A5	ABS4	turn absolute data	24	B5	TKN4	absolute	2 ⁴
A6	ABS5		2 ⁵	B6	TKN5	data	2 ⁵
A7	ABS6		2 ⁶	B7	TKN6		2 ⁶
A8	ABS7		27	B8	TKN7		27
A9	ABS8		2 ⁸	B9	COF	Counter overflow a	alarm
A10	ARST	Single-turn data reset		B10	TRST	Multi-turn reset	data
A11	GND	0 V*		B11	GND	0 V*	
A12	Vcc	12 to 24 VDC*		B12	Vcc	12 to 24 \	/DC*
A13	SHIELD	Shield		B13	SHIELD	Shield	

* We recommend connecting both Vcc and GND. Note: Connector Model PS-D4C26 (Hood: PS-HD26) (Japan Aviation Electronics Industry, Ltd.) Connector: PS-26PE-D4T_-M_ (Straight Model) PS-26PE-D4LT_-M_ (Angle Model) (Japan Aviation Electronics Industry, Ltd.)

Pin Arrangement

A13			B13				
A12			B12				
A11			B11				
A10			B10				
A9			B9				
A8 _			B8				
A7			B7				
A6 🕇			B6				
A5			B5				
A4			B4				
A3			B3				
A2			B2				
A1			B1				

Note: Normally connect GND to 0 V or to an external ground.

E6C-N

Programmable Controller Connection Example

Connection to the CPM1A



Safety Precautions

Refer to Warranty and Limitations of Liability.

🔥 WARNING

This product is not designed or rated for ensuring safety of persons either directly or indirectly. Do not use it for such purposes.



Precautions for Correct Use

Do not use the Encoder under ambient conditions that exceed the ratings.

Wiring

Spurious pulses may be generated when power is turned ON and OFF. Wait at least 0.1 s after turning ON the power to the Encoder before using the connected device, and stop using the connected device at least 0.1 s before turning OFF the power to the Encoder. Also, turn ON the power to the load only after turning ON the power to the Encoder.

E6C-N

(Unit: mm)

Dimensions

Tolerance class IT16 applies to dimensions in this datasheet unless otherwise specified.

Encoder



E6C-NN5CA (Pre-wired Model) E6C-NN5CA-C (Connector Model)



Accessories (Order Separately)

Couplings

E69-C06B E69-C68B E69-C610B E69-C06M Refer to *Accessories* for details. Flanges E69-FCA E69-FCA02 Servo Mounting Bracket E69-2

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