# E6D-C

CSM\_E6D-C\_DS\_E\_5\_2

## **High-resolution Encoder**

- Incremental model
- External diameter of 55 mm.
- Resolution of up to 6,000 ppr.





Be sure to read *Safety Precautions* on page 4.

### **Ordering Information**

#### Encoders [Refer to Dimensions on page 4.]

Power supply voltage	Output configuration	Resolution (pulses/rotation)	Model
5 VDC	Voltage output	1,000	E6D-CWZ1E (resolution) 0.5M Example: E6D-CWZ1E 1000P/R 0.5M
		2,000	
		3,600	
		5,000	
		6,000	
12 VDC	Open-collector output	1,000	E6D-CWZ2C (resolution) 0.5M Example: E6D-CWZ2C 1000P/R 0.5M
		2,000	
		3,600	
		5,000	
		6,000	

Note: In addition to the models listed at the left, models with either voltage outputs or open-collector outputs are also available with the following resolutions (pulses/rotation): 720, 800, 1,024, 1,200, 1,500, 1,800, 2,048, 2,500, 3,000, 3,200, and 4,096.

#### Accessories (Order Separately) [Refer to Dimensions on Rotary Encoder Accessories.]

Name	Model	Remarks
	E69-C06B	Provided with the product.
Couplings	E69-C68B	Different end diameter
Couplings	E69-C610B	Different end diameter
	E69-C06M	Metal construction
Servo Mounting Bracket	E69-2	Provided with the product.

Refer to Accessories for details.

## **Ratings and Specifications**

Item	Model	E6D-CWZ1E	E6D-CWZ2C		
Power supply voltage		5 VDC ±5%, ripple (p-p): 5% max. 12 VDC ±10%, ripple (p-p): 5% max.			
Current consu	mption*1	150 mA max.			
Resolution (pu	lses/rotation)	1,000, 2,000, 3,600, 5,000, 6,000			
Output phases	<b>.</b>	Phases A, B, and Z			
Output configuration Voltage output		Voltage output	Open-collector output		
Output capacity		Output resistance: 1 k $\Omega$ Sink current: 35 mA max. Residual voltage: 0.7 V max. (at sink current of 10 mA)	Applied voltage: 30 VDC max. Sink current: 35 mA max. Residual voltage: 1 V max. (at sink current of 35 mA) Residual voltage: 0.7 V max. (at sink current of 10 mA)		
Maximum resp quency*2	onse fre-	200 kHz			
Phase differen outputs	ce between	90°±25° between A and B (1/4 T ± 0.07 T)			
Rise and fall ti	mes of output	1 μs max.			
Starting torque	arting torque 9.8 mN·m max.				
Moment of inertia		$3 \times 10^{-6} \text{ kg} \cdot \text{m}^2 \text{ max}.$			
Shaft loading Radial Thrust		50 N (20 N to maintain accuracy)			
		30 N (10 N to maintain accuracy)			
Maximum pern speed	n permissible 12,000 r/min				
Ambient temperature range Operation		Operating: –10 to 70°C (with no icing), Storage: –25 to 80°C (with no icing)			
Ambient humic	dity range	Operating/Storage: 35% to 85% (with no condensation)			
Insulation resi	stance	Excluded because of capacitor ground.			
Dielectric stre	ngth	Excluded because of capacitor ground.			
Vibration resis	tance	Destruction: 10 to 55 Hz, 1.5-mm double amplitude for 2 hours each in X, Y, and Z directions			
Shock resistar	nce	Destruction: 500 m/s <sup>2</sup> 3 times each in X, Y, and Z directions			
Degree of prot	ection*3	IEC 60529 IP50			
Connection me	ethod	Pre-wired Models (Standard cable length: 0.5 m)			
Material		Case: Zinc alloy, Main unit: Aluminum, Shaft: SUS303, Mounting Bracket: Galvanized iron			
Weight (packe	d state)	Approx. 280 g			
Accessories		E69-C06B Coupling, E69-2 Servo Mounting Bracket, Hexagonal wrench, Instruction manual			

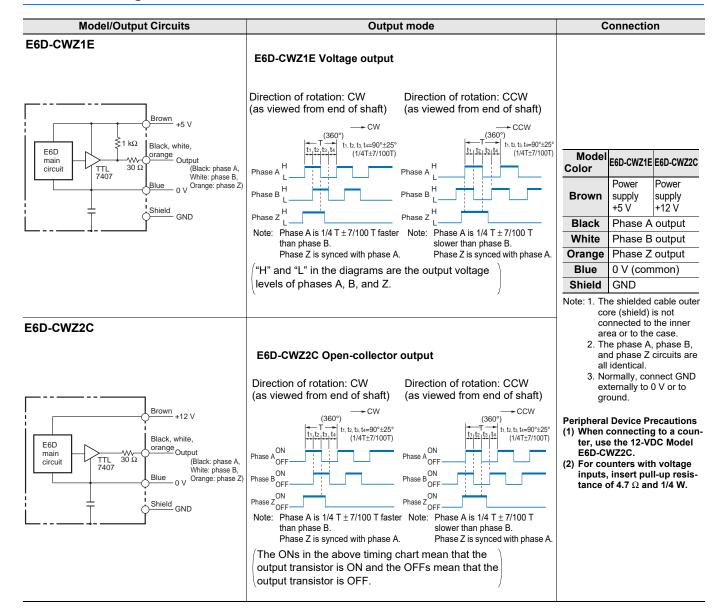
Maximum electrical response speed (rpm) = 

Maximum response frequency - ×60

<sup>\*1.</sup> An inrush current of approximately 2 A will flow for approximately 50 μs when the power is turned ON.
\*2. The maximum electrical response speed is determined by the resolution and maximum response frequency as follows:

This means that the Rotary Encoder will not operate electrically if its speed exceeds the maximum electrical response speed. \*3. No protection is provided against water or oil.

#### I/O Circuit Diagrams



#### **Safety Precautions**

#### Refer to Warranty and Limitations of Liability.



This product is not designed or rated for ensuring safety of persons either directly or indirectly. Do not use it for such purposes.



#### **Precautions for Correct Use**

Do not use the Encoder under ambient conditions that exceed the ratings.

#### Wiring

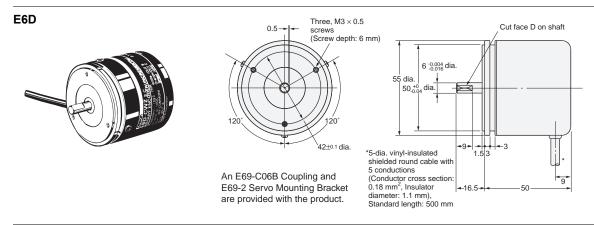
Spurious pulses may be generated when power is turned ON and OFF. Wait at least 0.1 s after turning ON the power to the Encoder before using the connected device, and stop using the connected device at least 0.1 s before turning OFF the power to the Encoder. Also, turn ON the power to the load only after turning ON the power to the Encoder.

(Unit: mm)

#### **Dimensions**

Tolerance class IT16 applies to dimensions in this datasheet unless otherwise specified.

#### **Encoder**



#### **Accessories (Order Separately)**

Refer to Accessories for details.

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